

Fig. 1

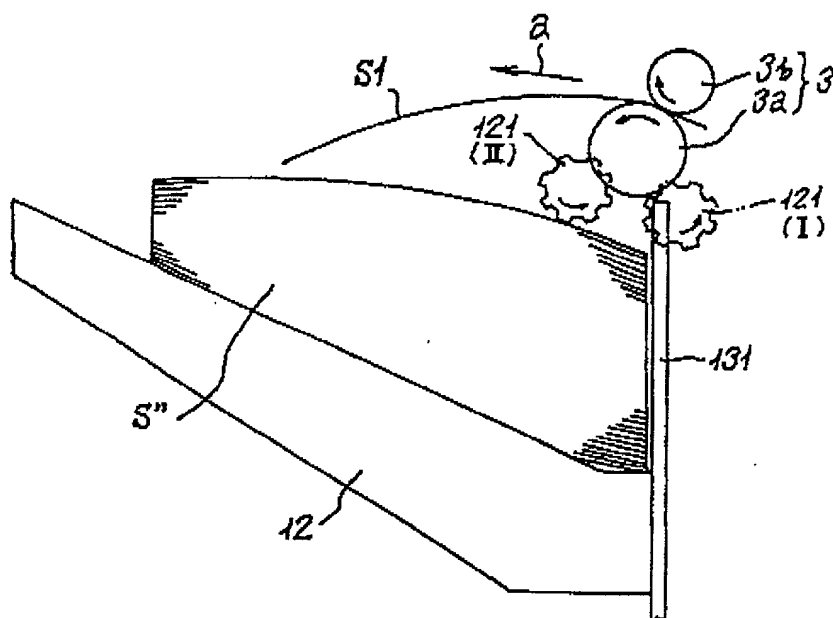
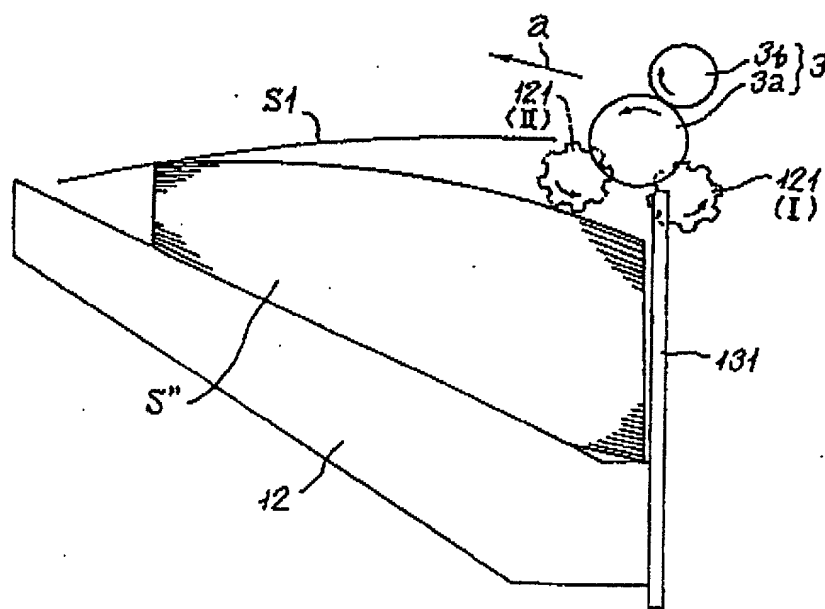
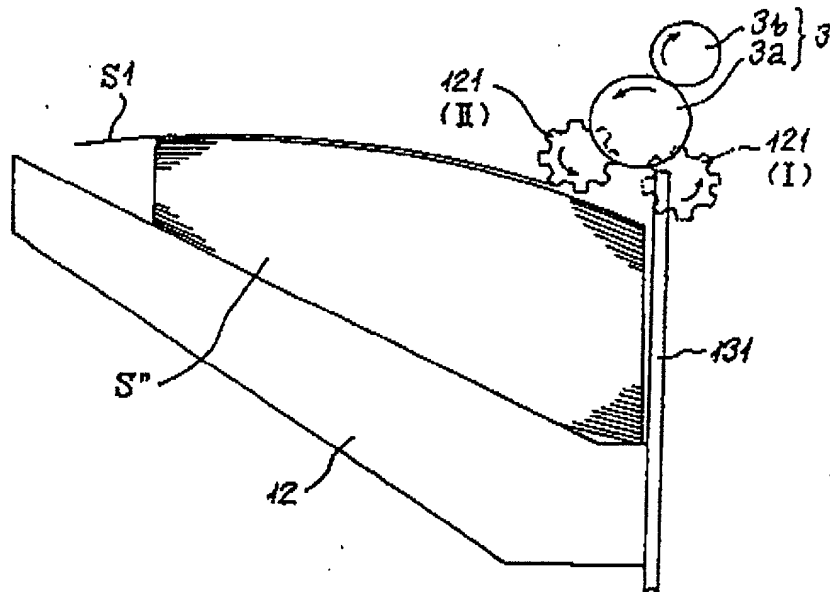


Fig. 2



F i g . 3



F i g . 4

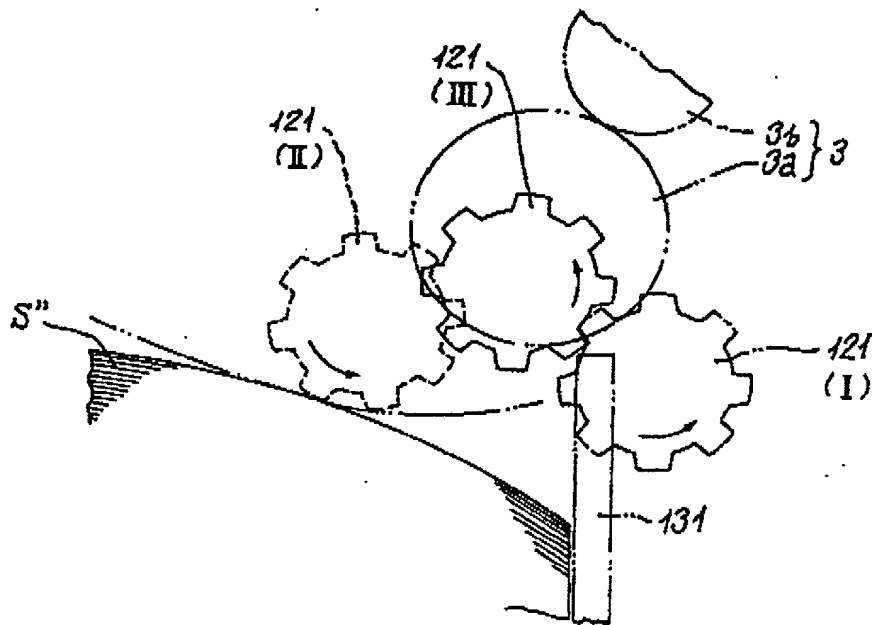


Fig. 5

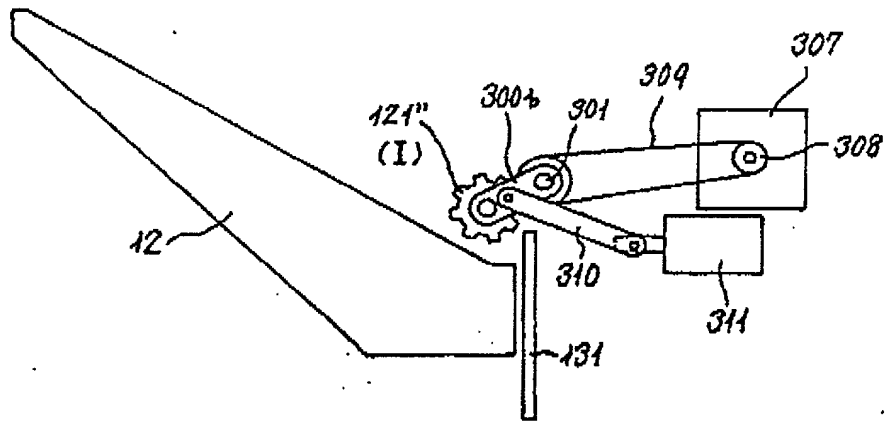


Fig. 6

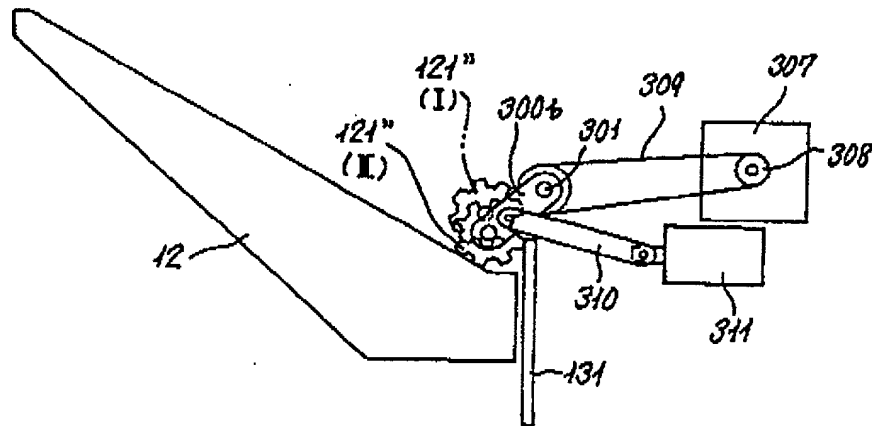








Fig. 11

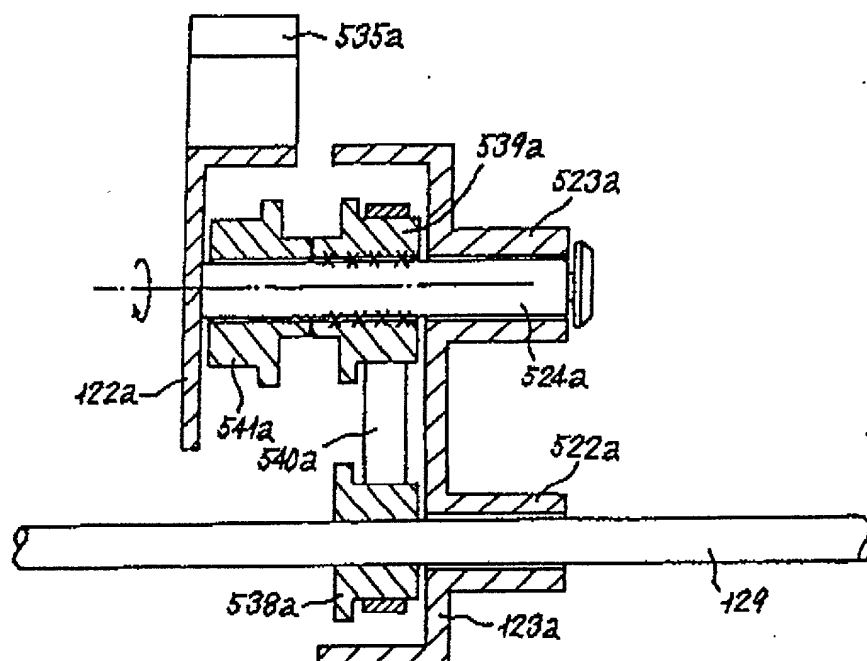
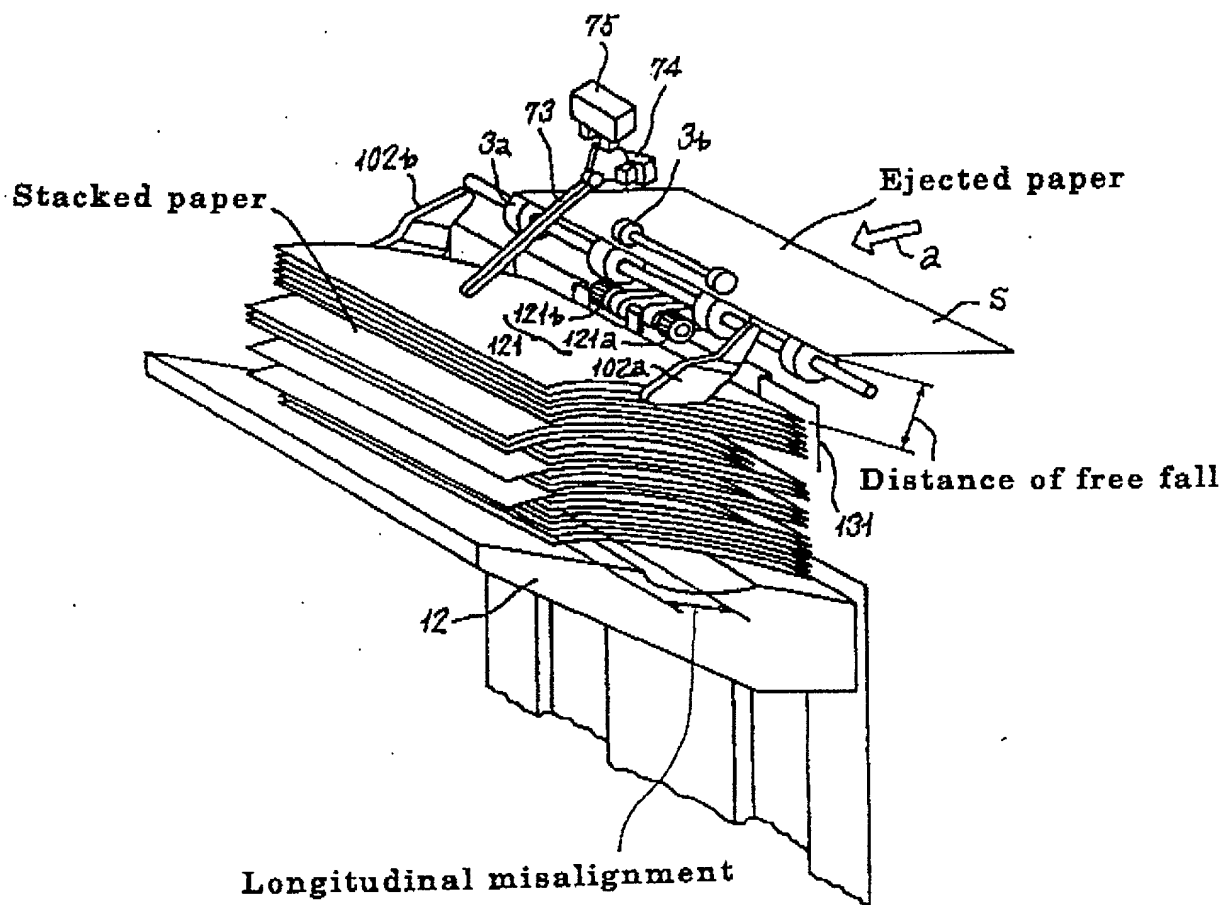


FIG. 11

Fig. 12



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Fig. 13

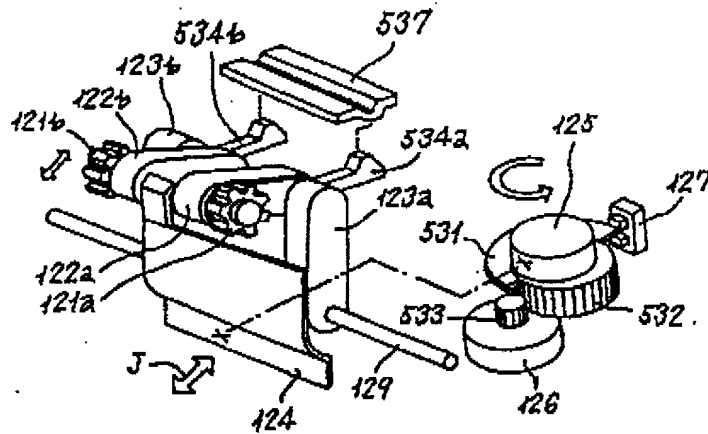


Fig. 14

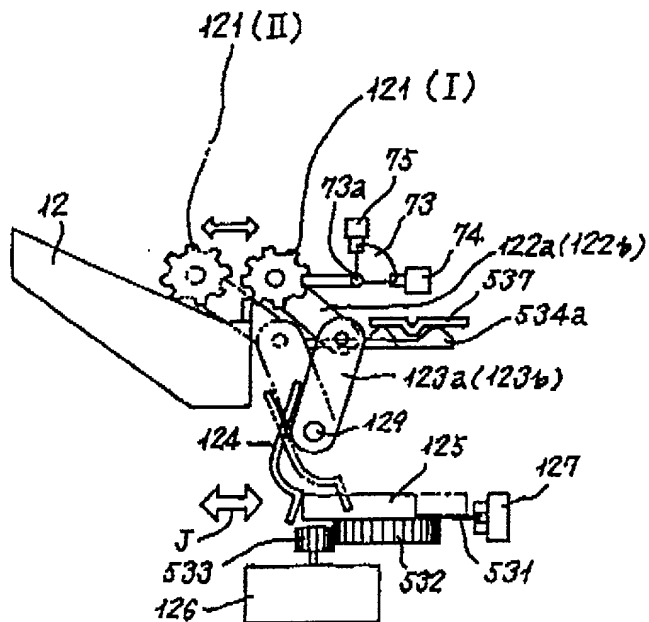


Fig. 15 (a)

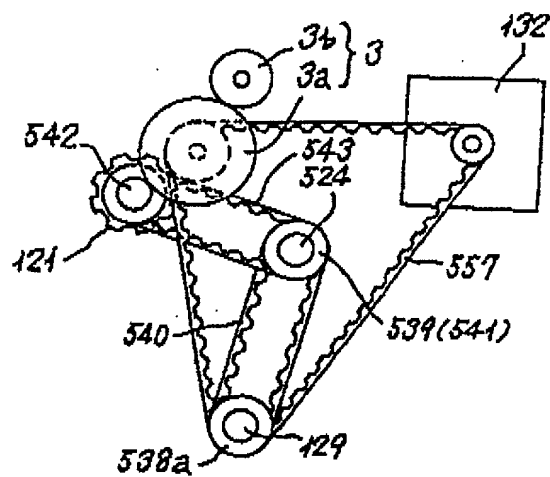


Fig. 15 (b)

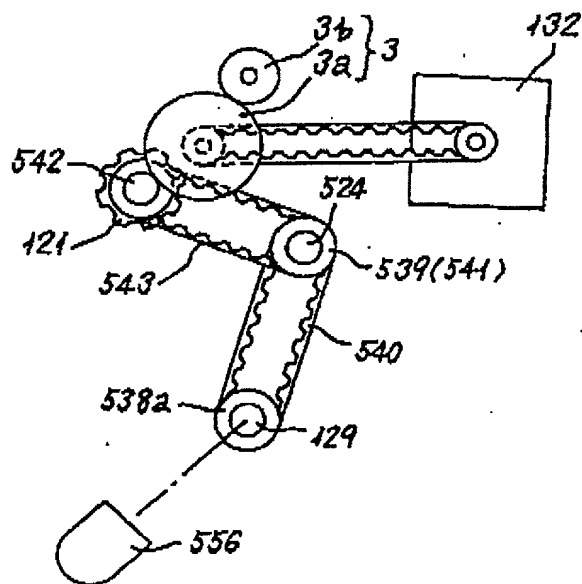
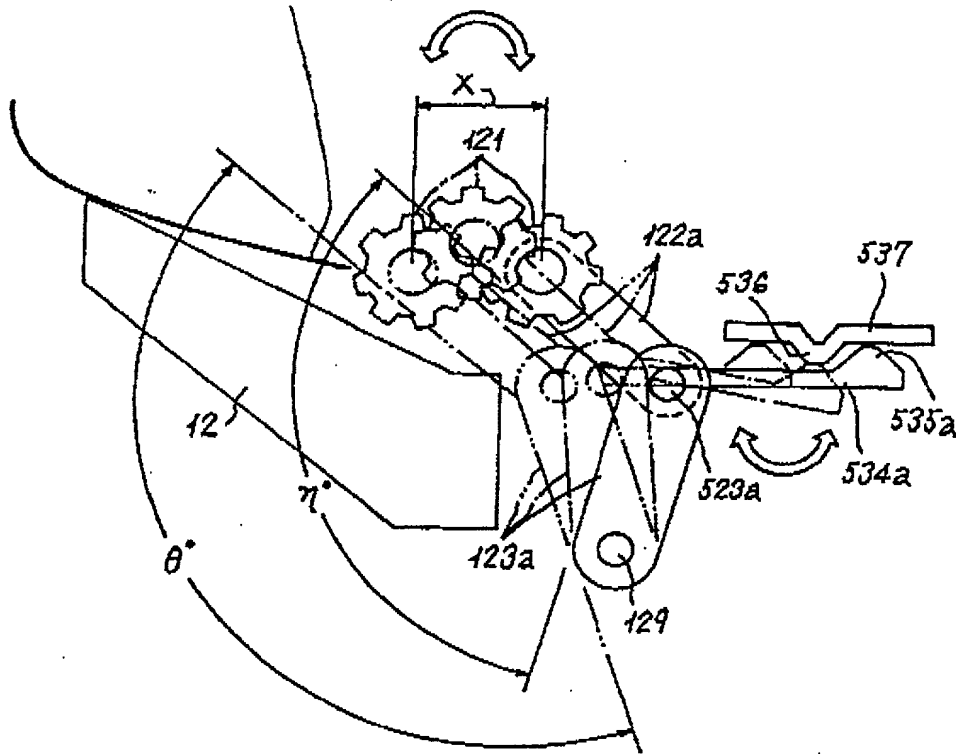


Fig. 16

Back end face-curved paper





[illegible]

Fig. 19

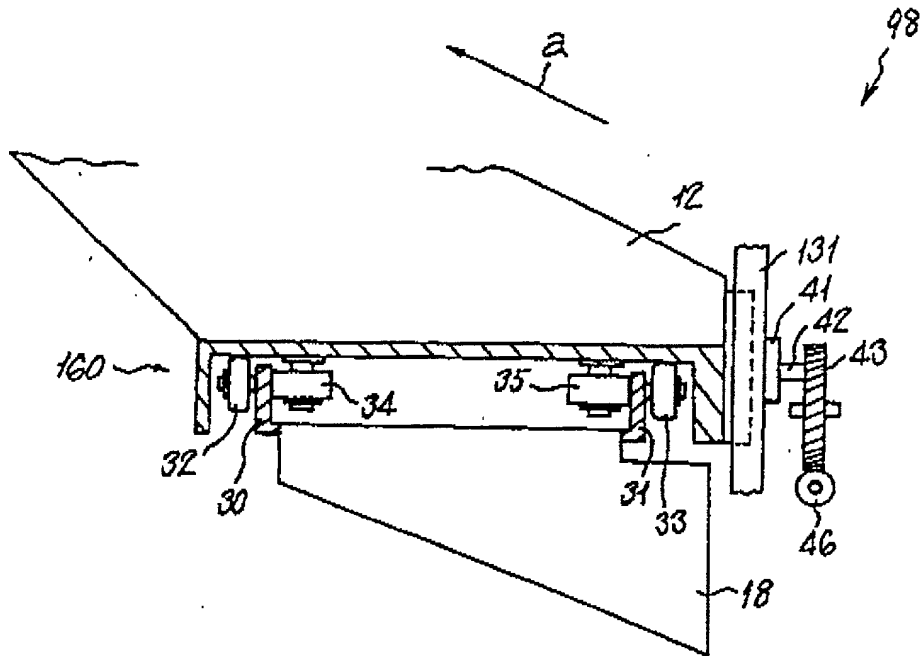


Fig. 20

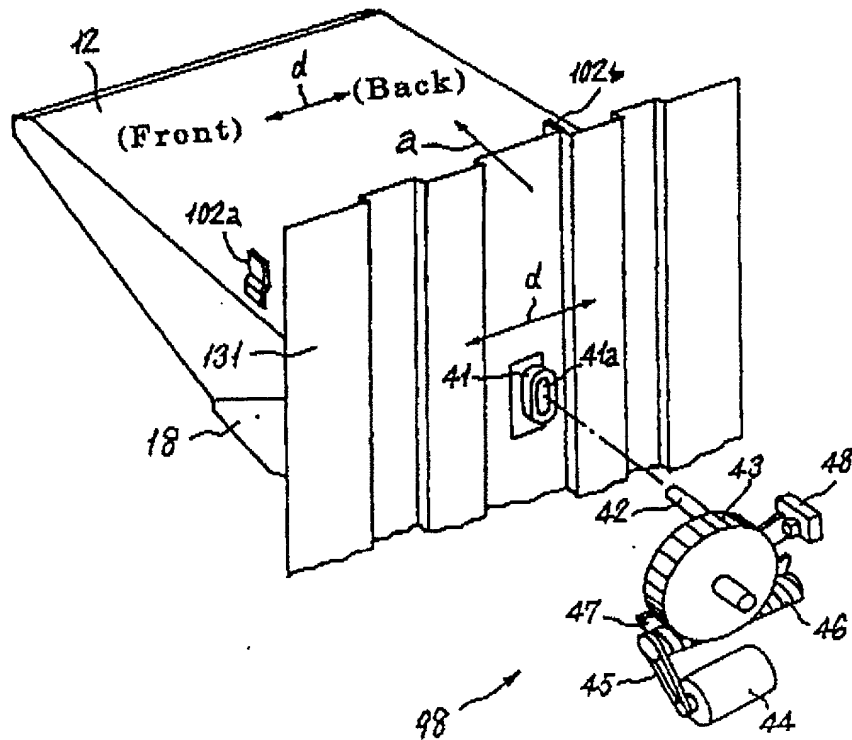
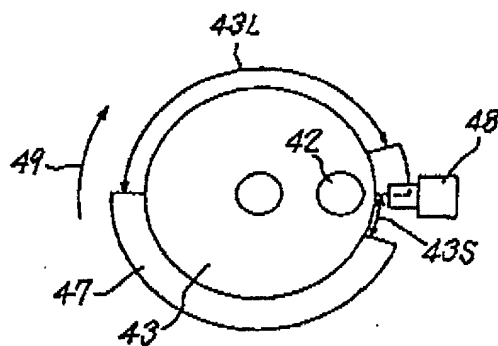
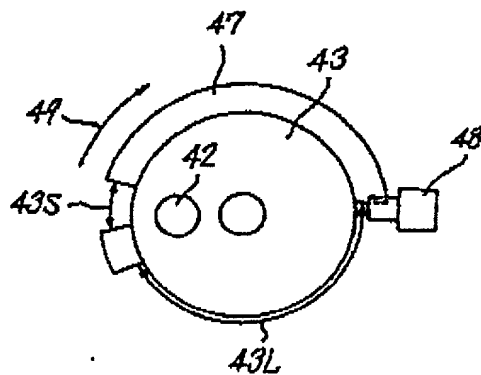


FIG. 19

F i g . 2 1



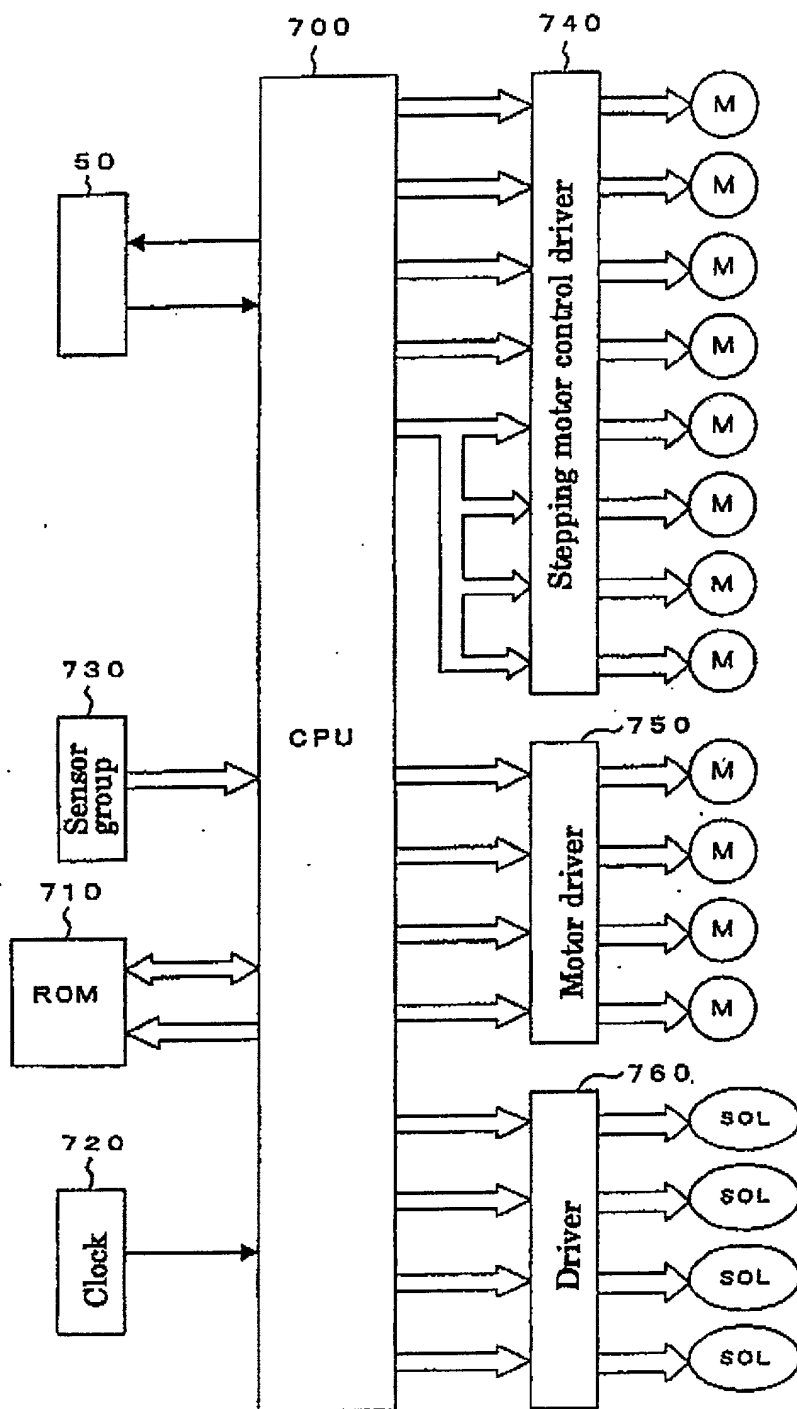
F i g . 2 2





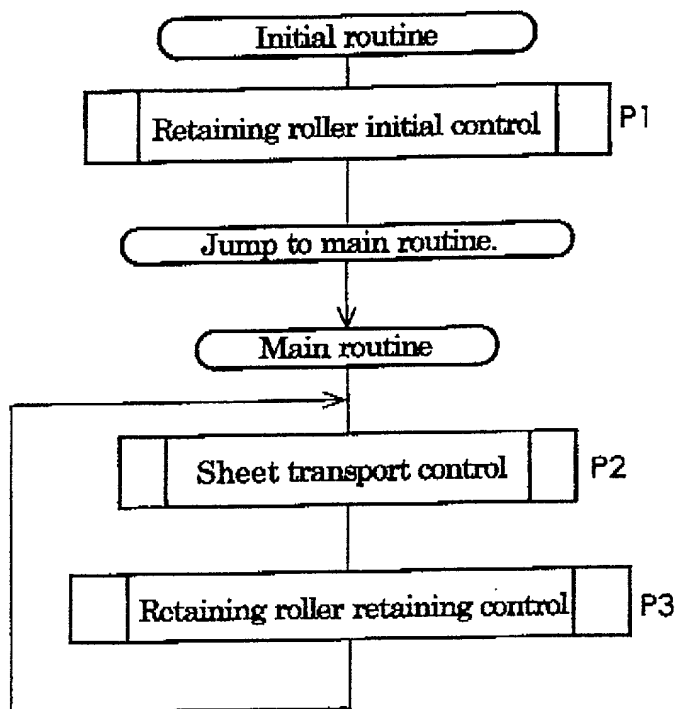


F i g . 2 4



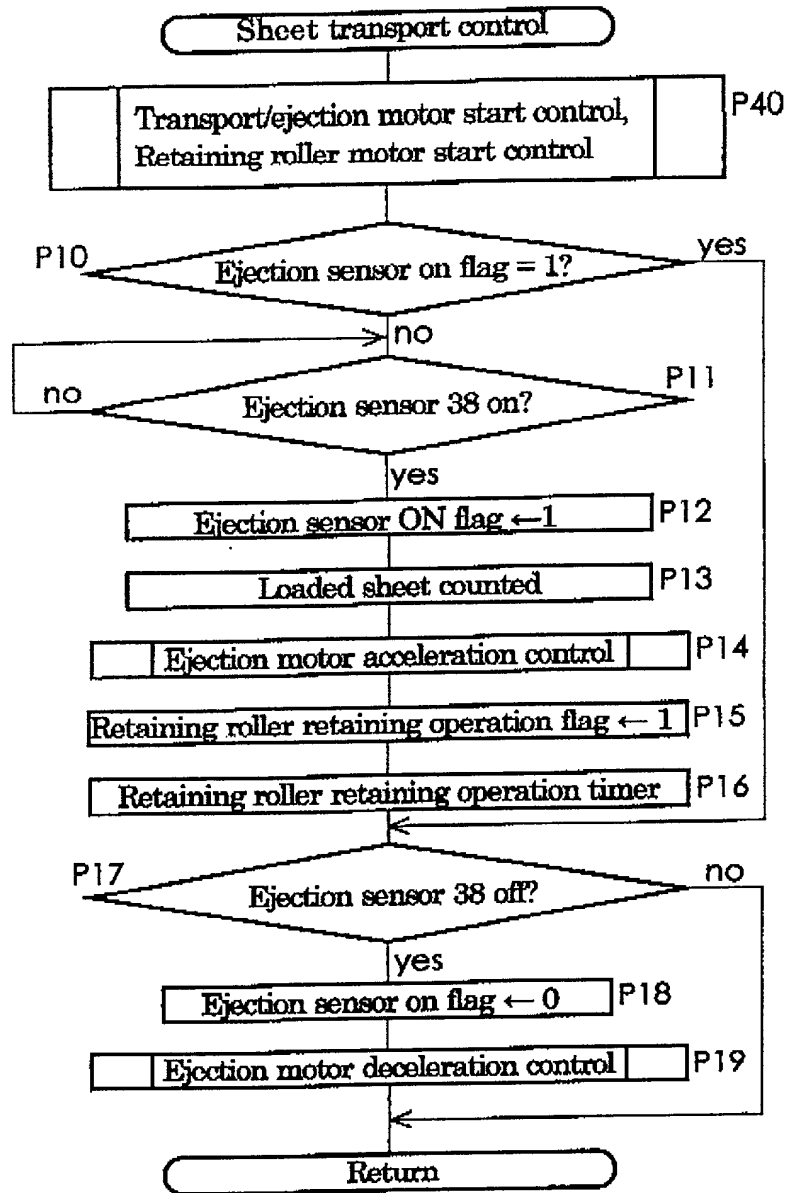
FOREF" 408/6660

F i g . 2 5



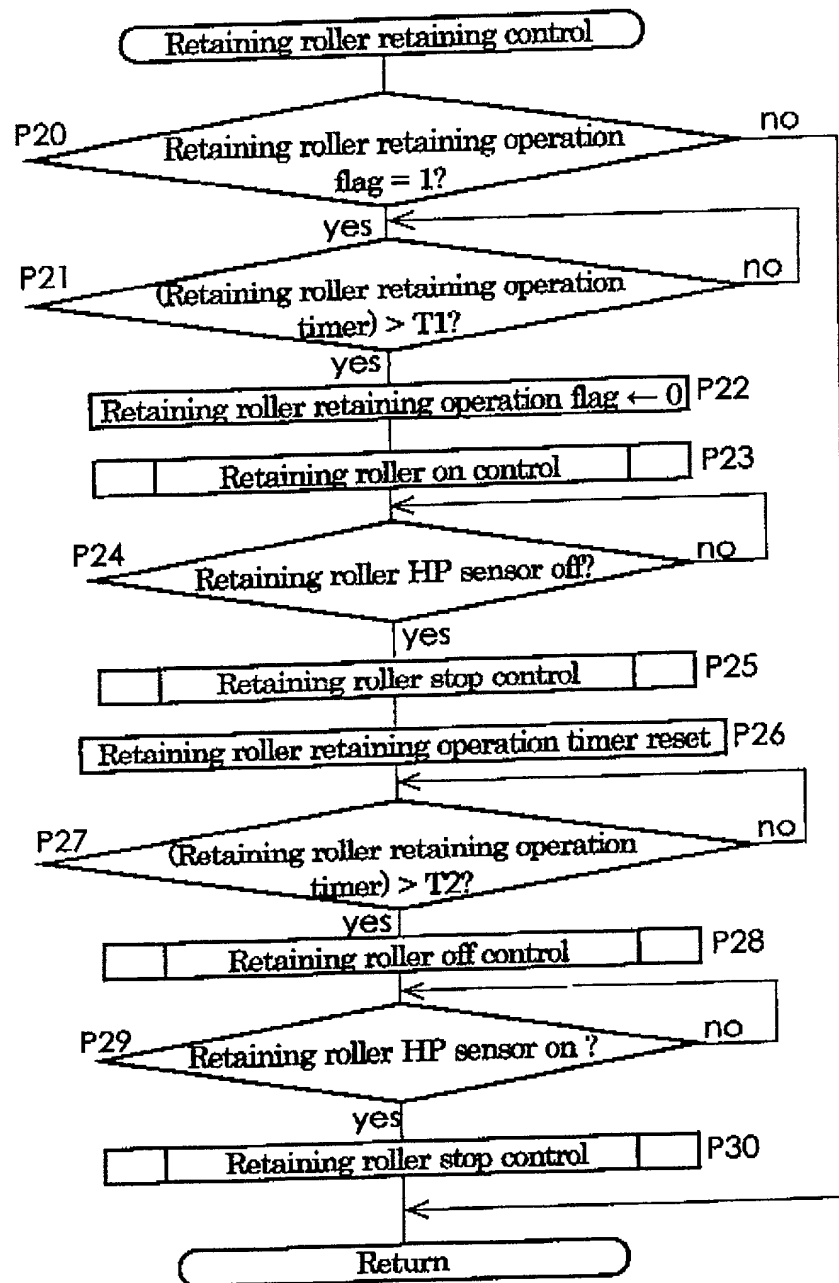
DOCKET # 216630US2

Fig. 26



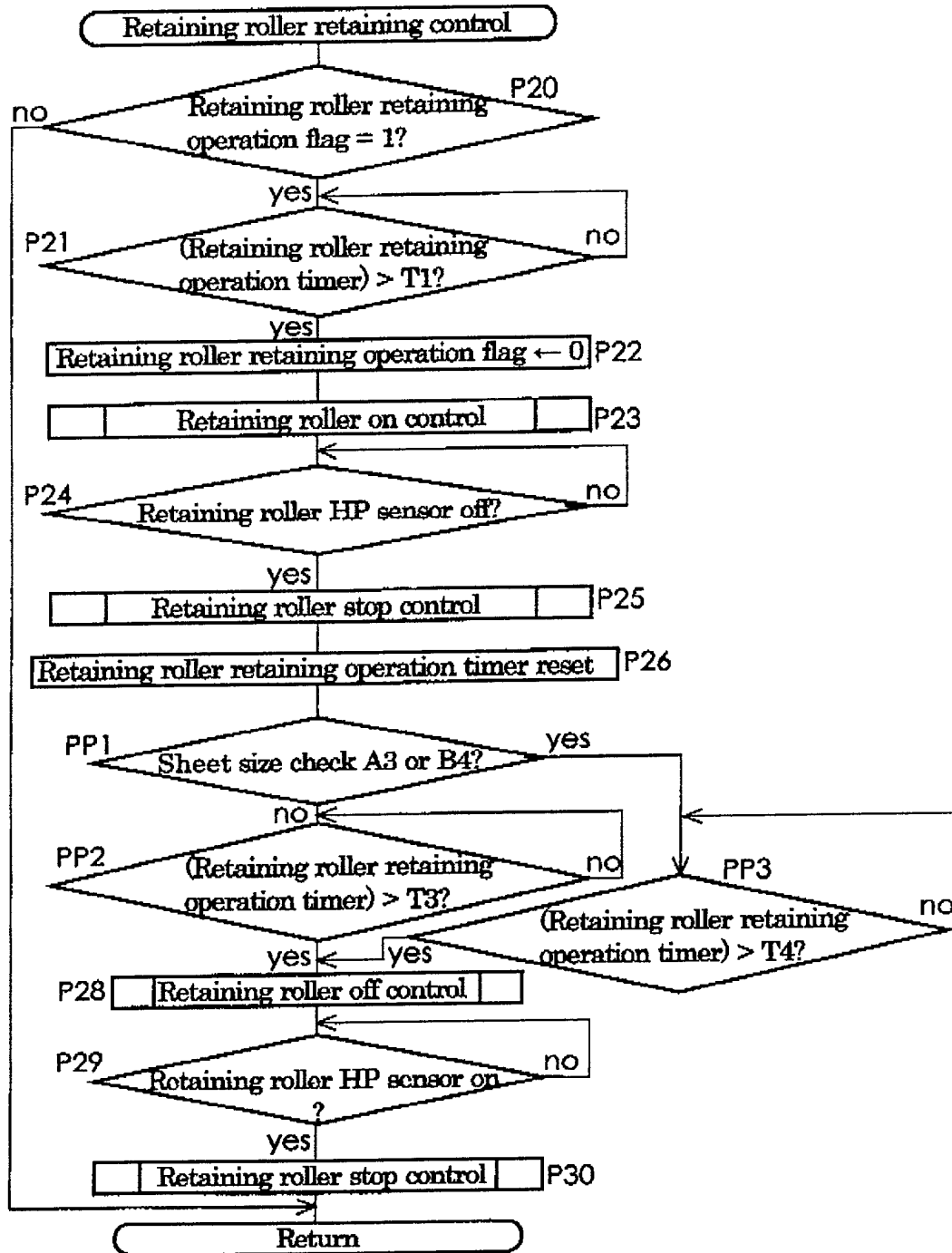
09997304-13004  
FOUO F-4086560

Fig. 27



09997304-113001  
FOUO 11-108/6660

F i g . 2 8



0997304-11001  
FOOT-40E/6660

Fig. 29

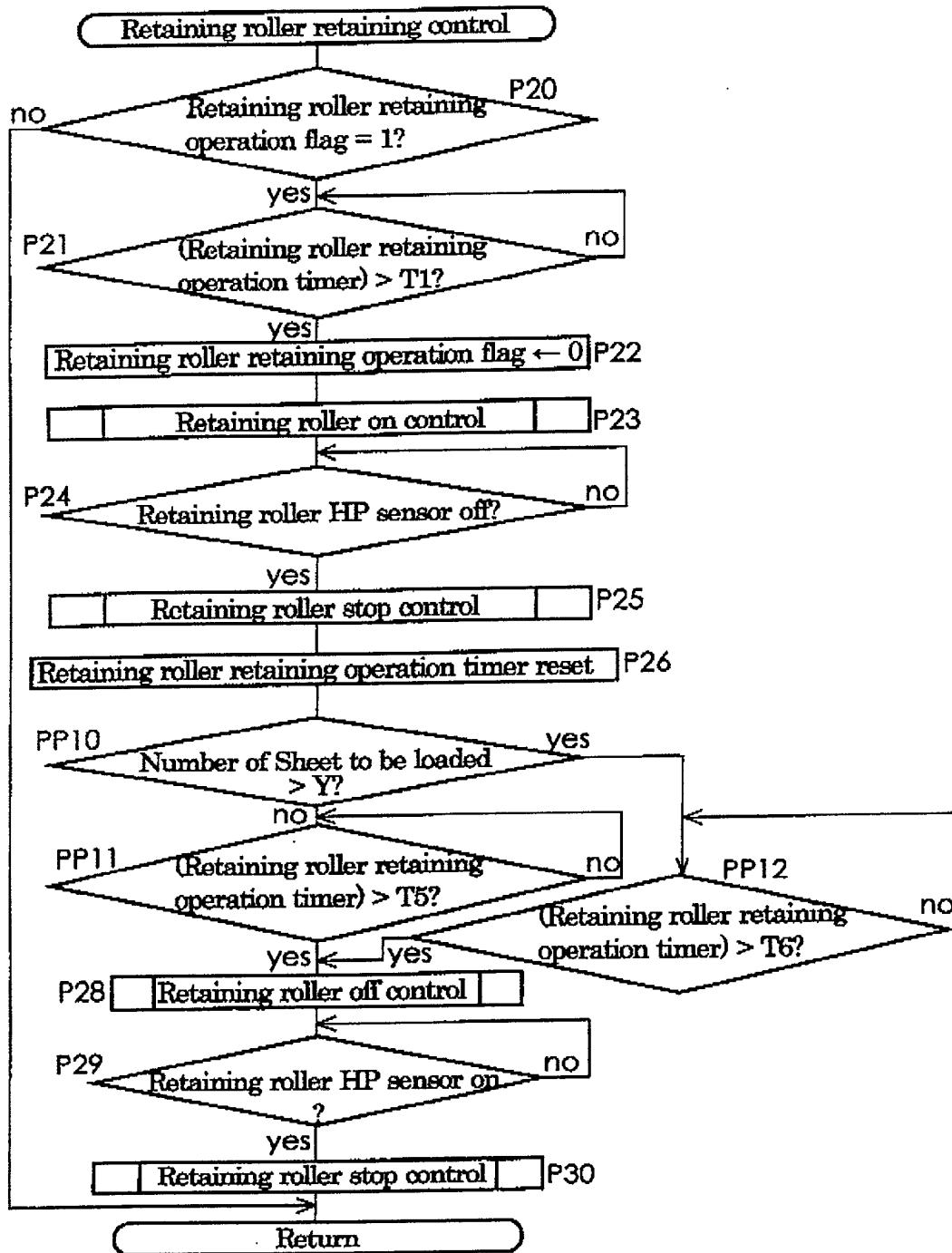
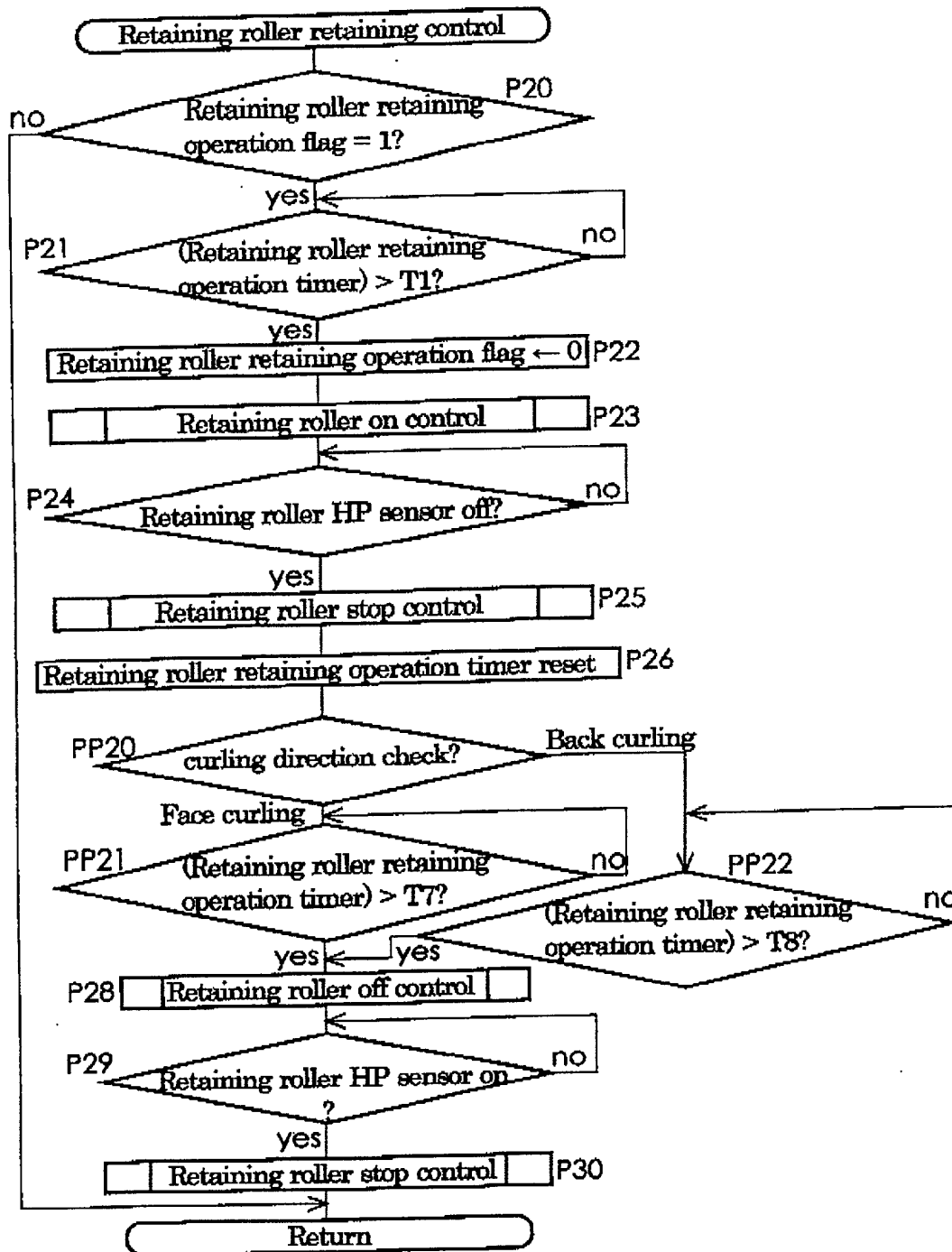


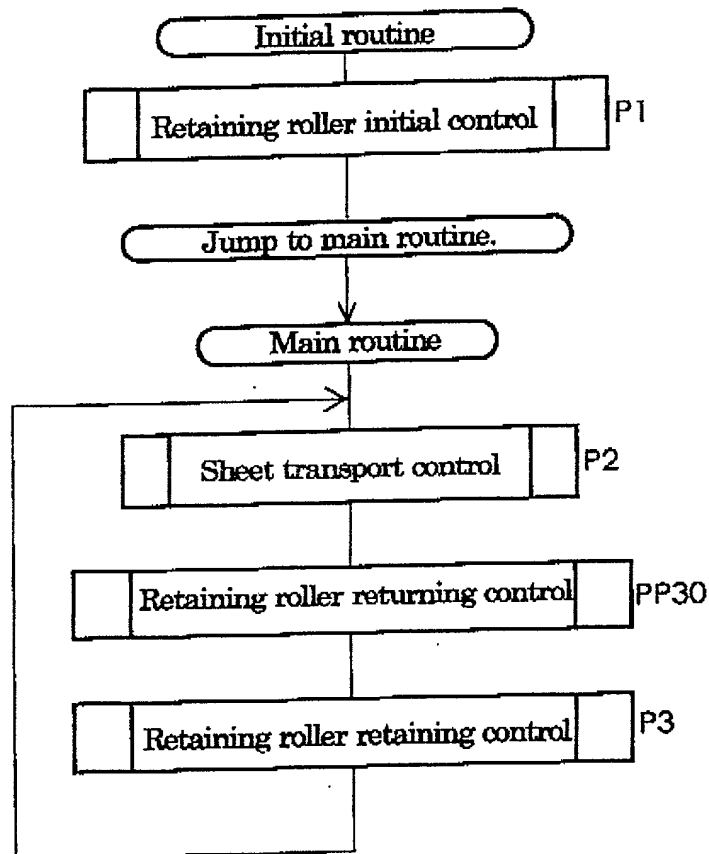
FIG. 29

Fig. 30



DOCKET: 40E/6660

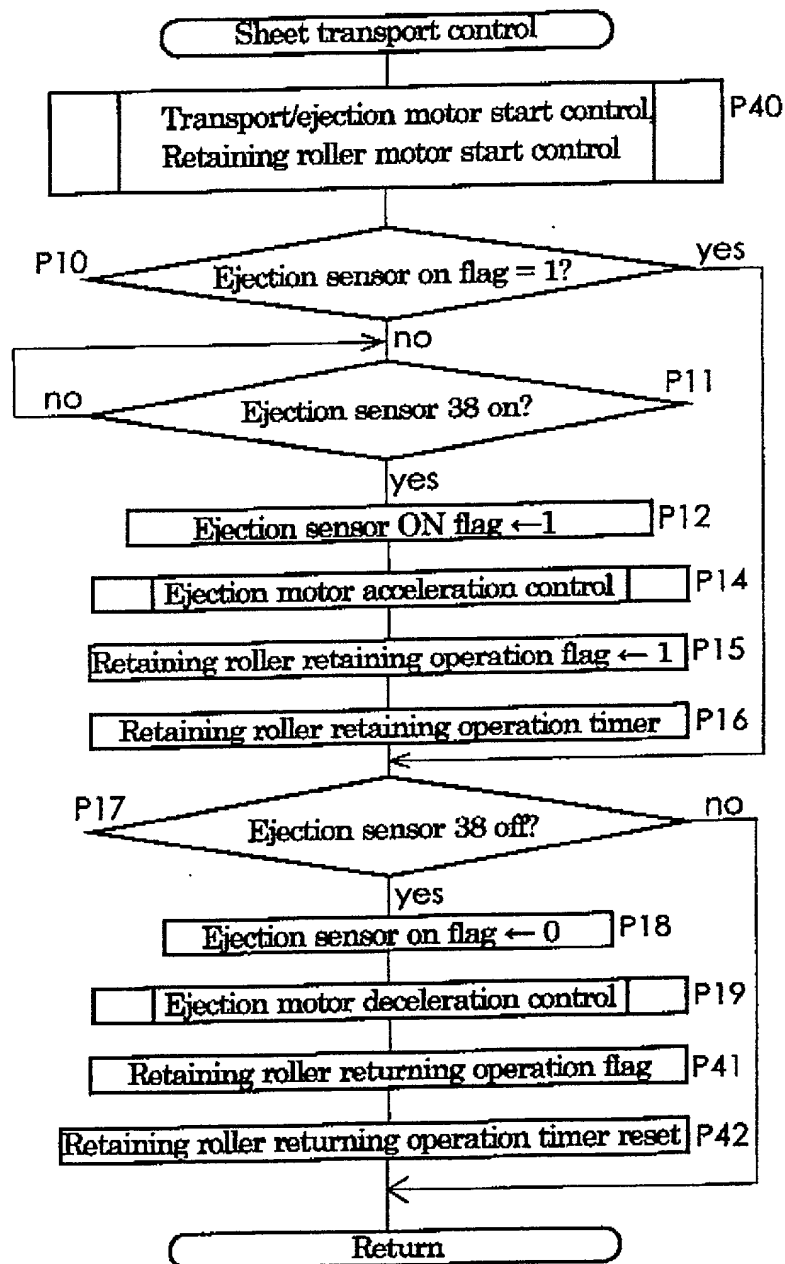
Fig. 31



0993304-1-3001



Fig. 32



FOOET"40E26660

Fig. 33

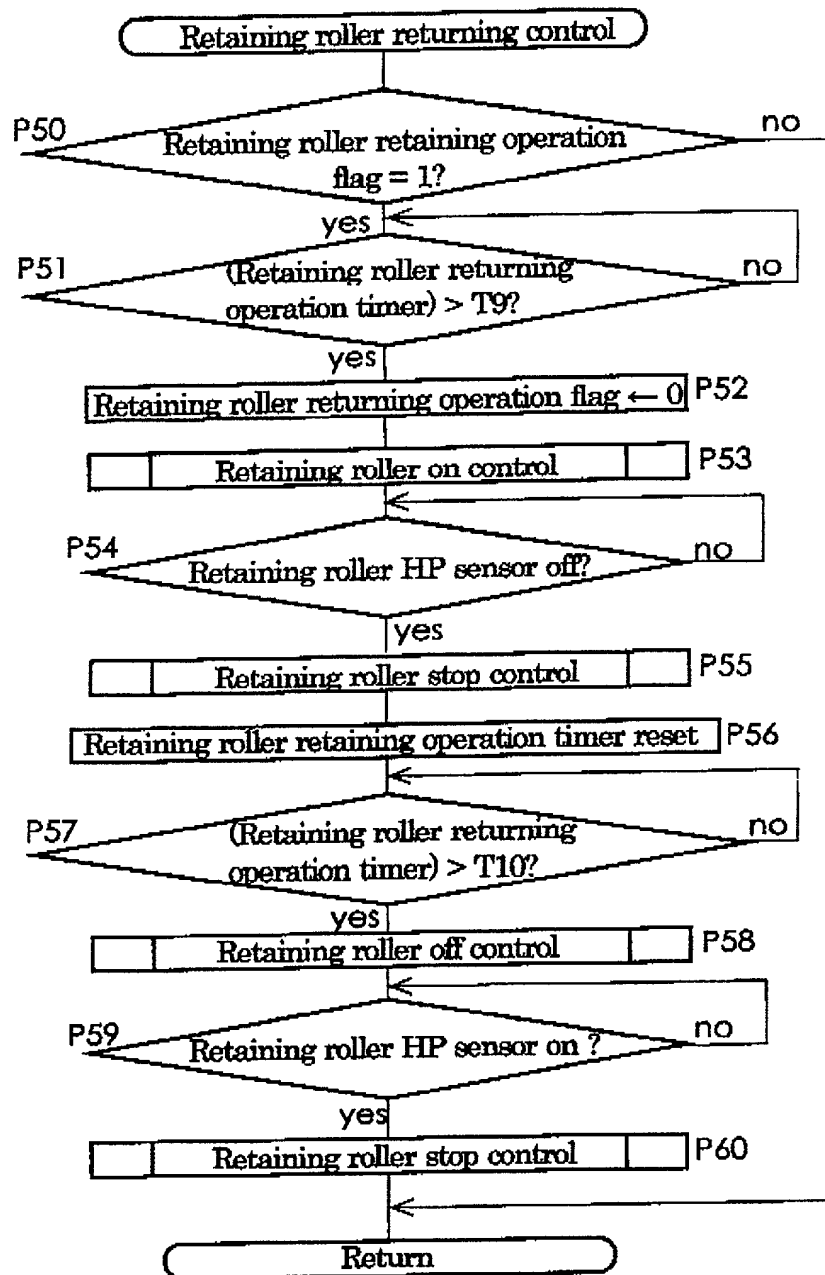
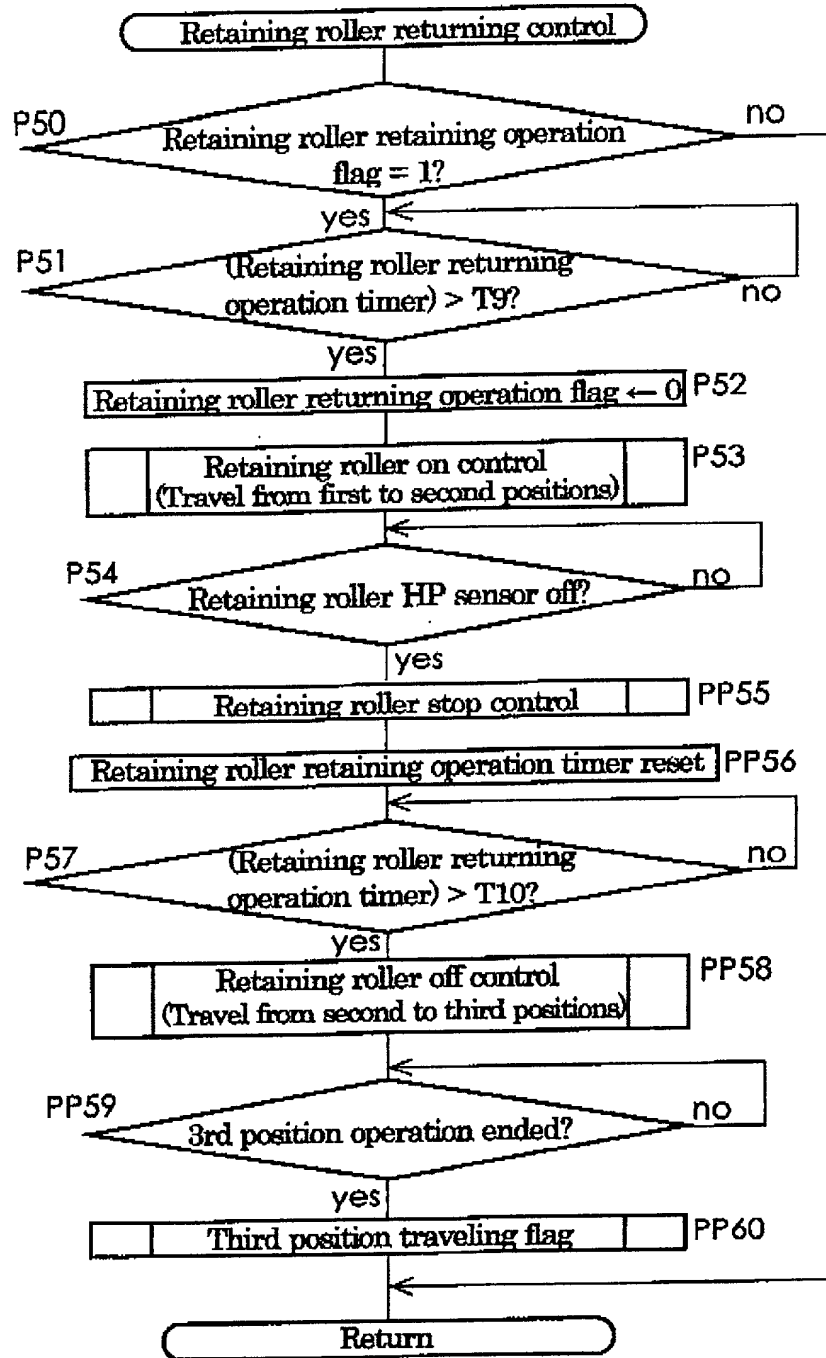


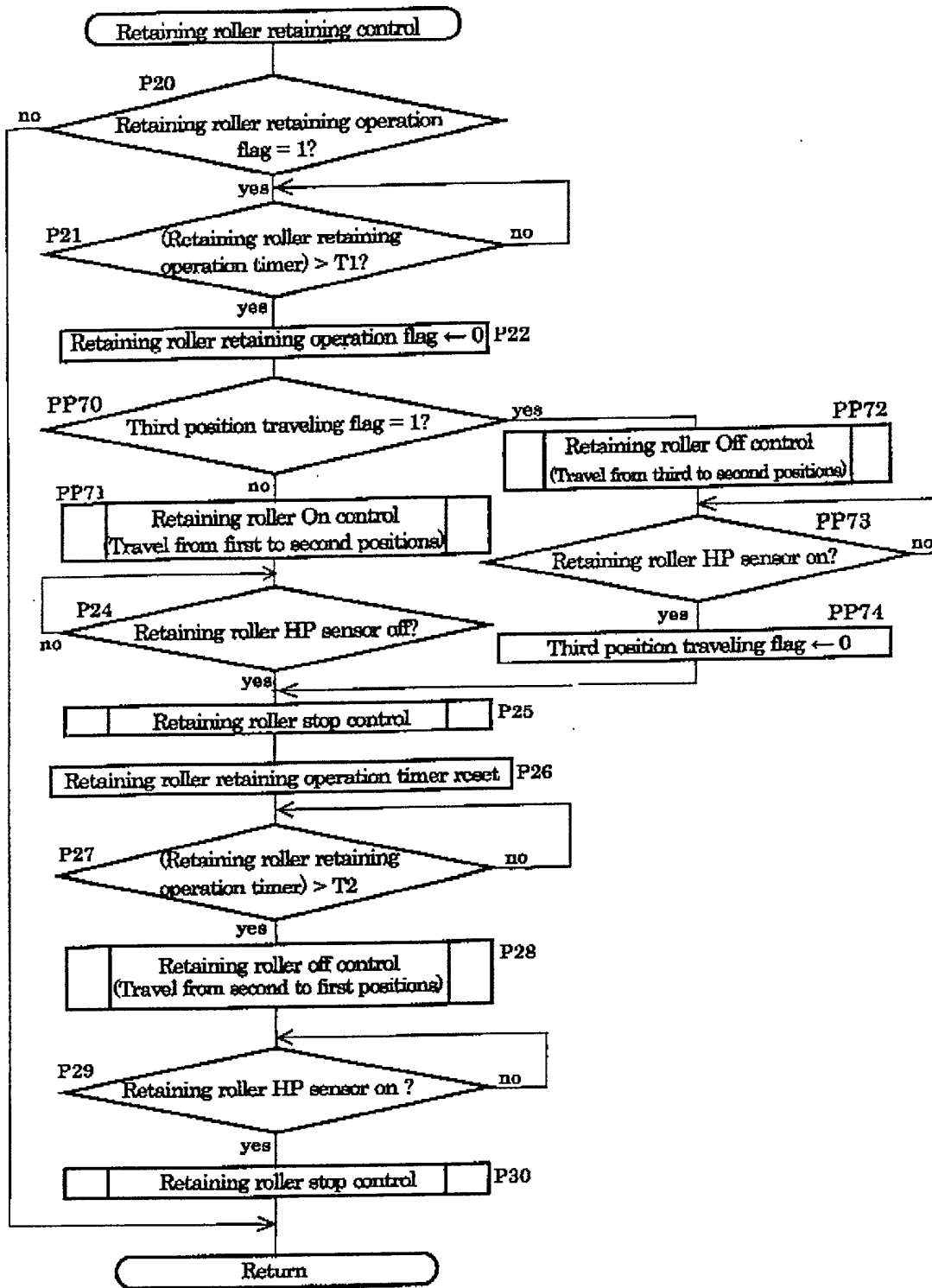
FIG. 33

Fig. 34



FOOTNOTES: 40E/6660

Fig. 35



DOCKET # 216630US2

Fig. 36

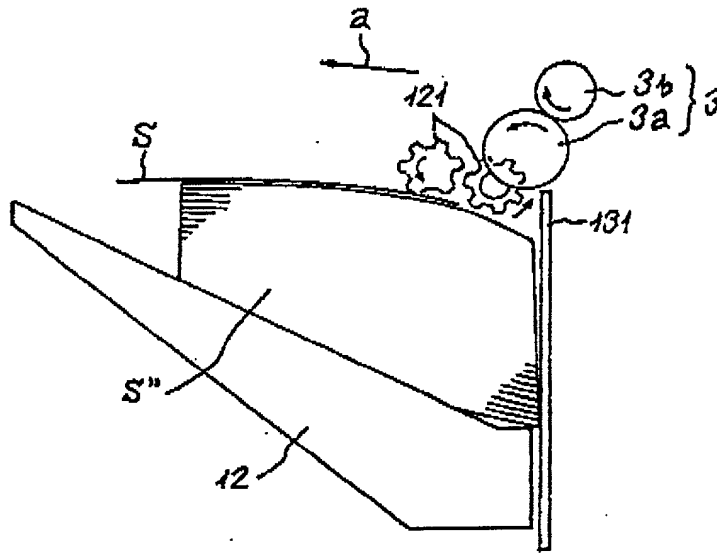


Fig. 37

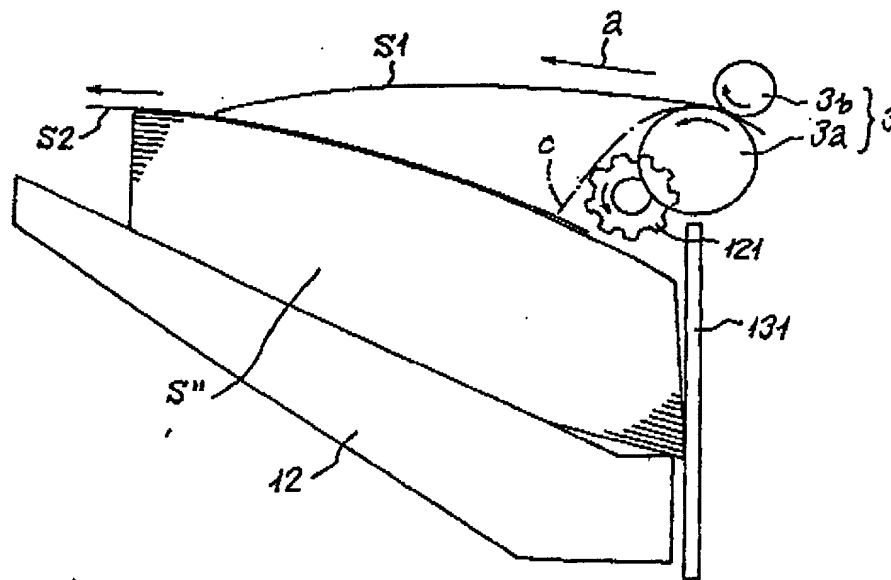
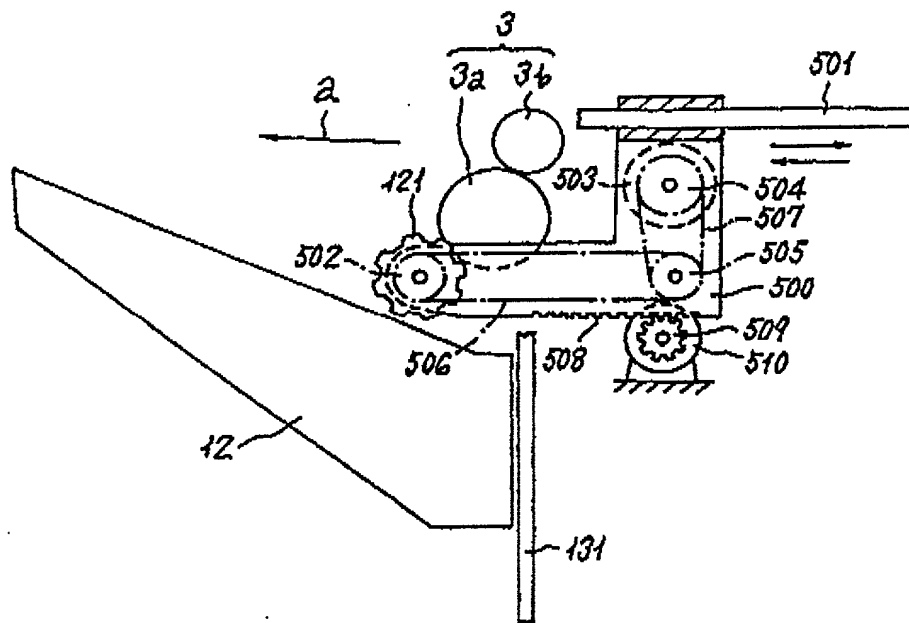
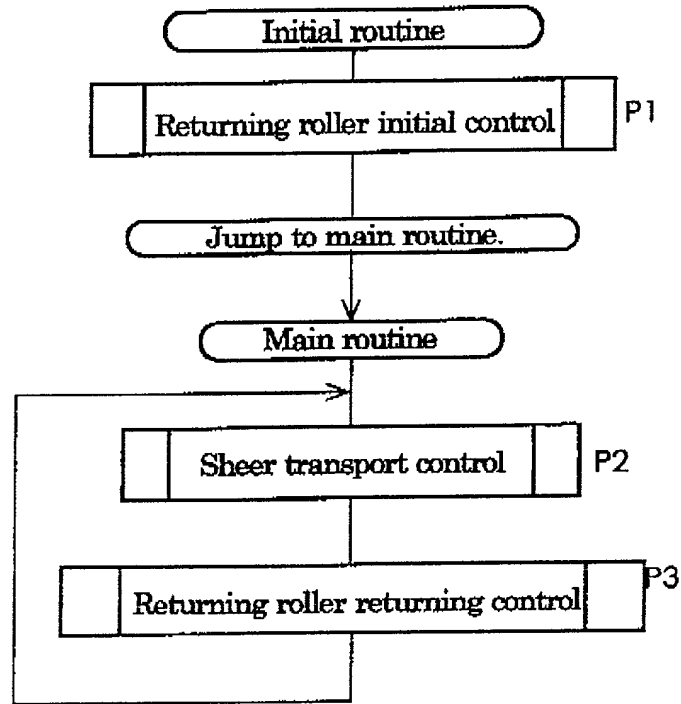


Fig. 38



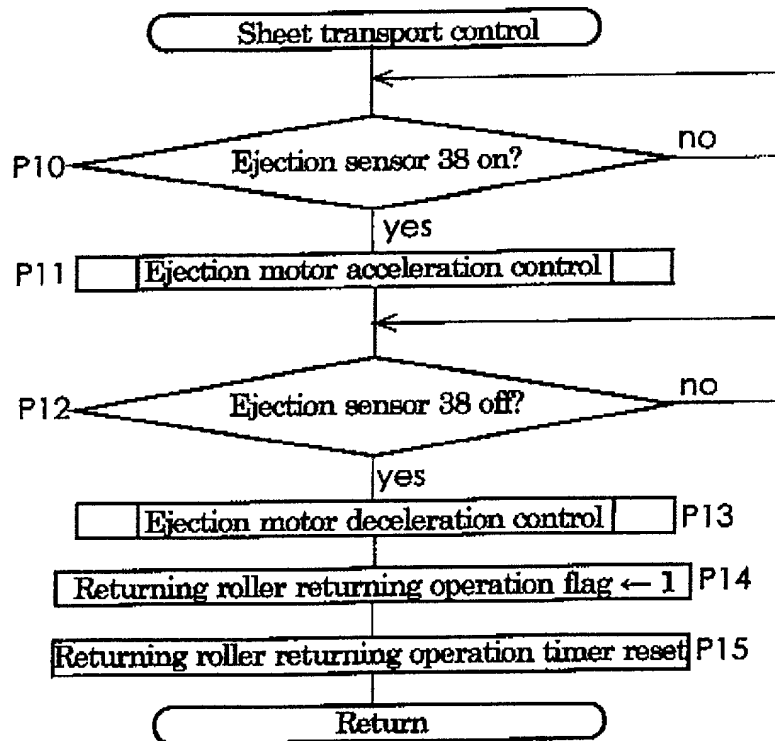
DOCKET # 216630US2

F i g . 3 9



TOEET" 40E/6660

F i g . 4 0



DOCKET "40E/6660"



Fig. 41

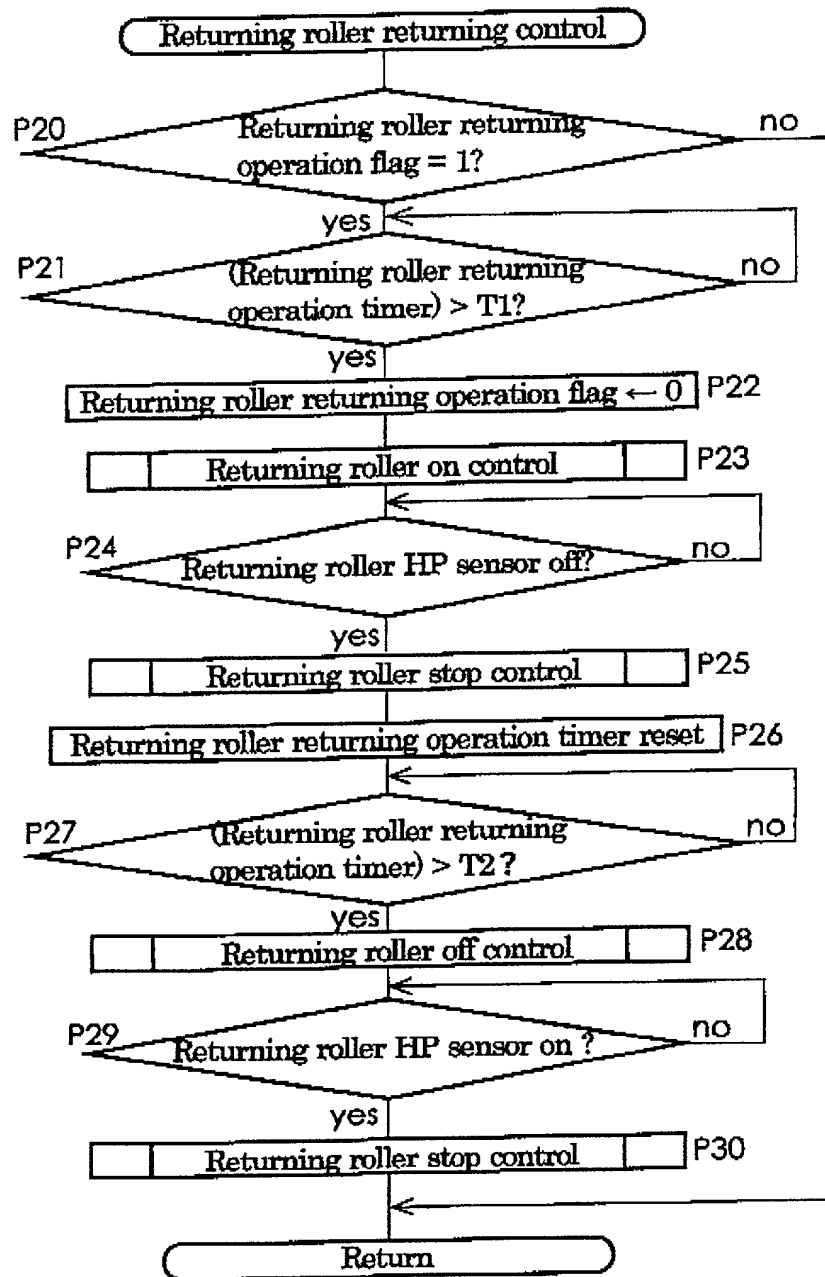
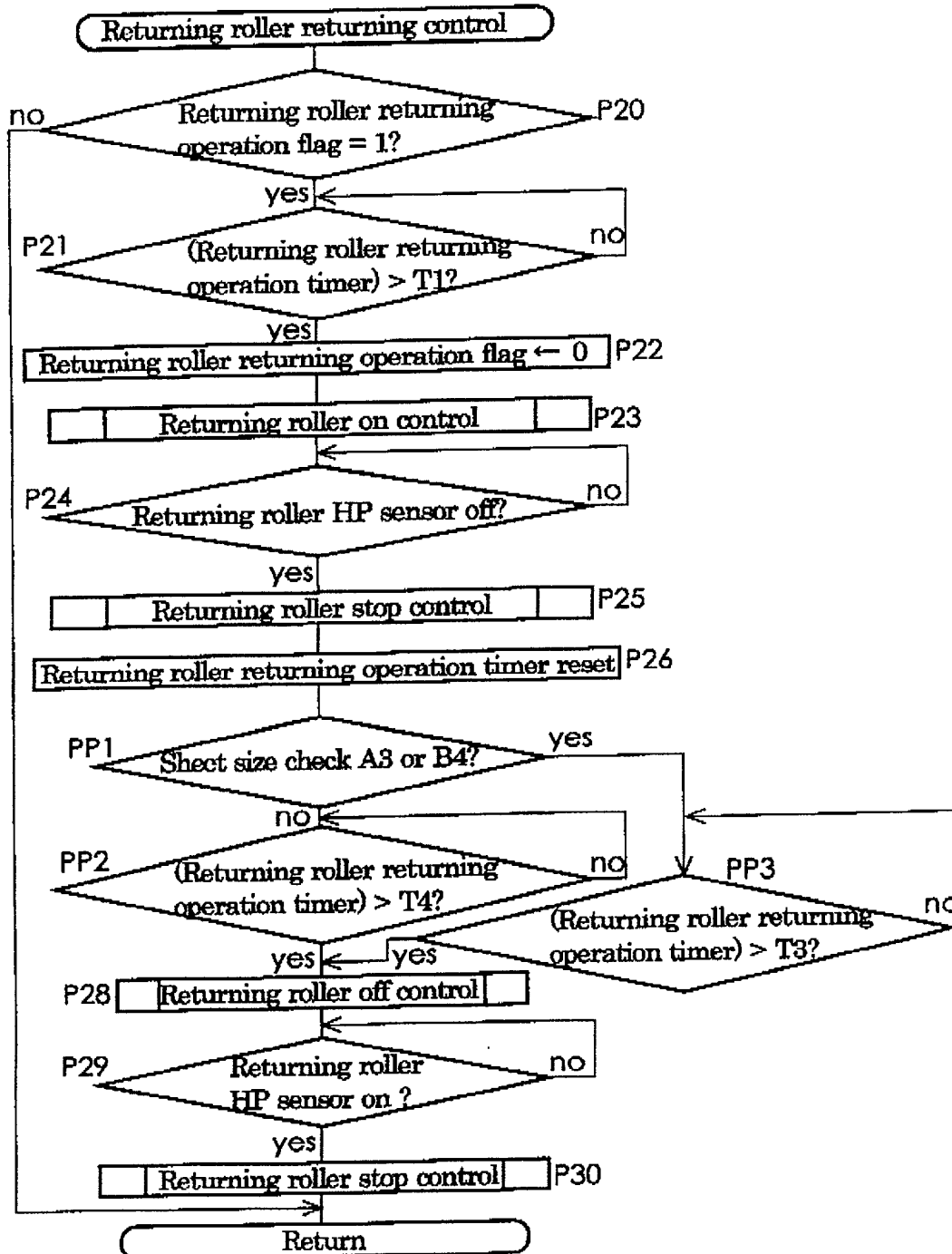


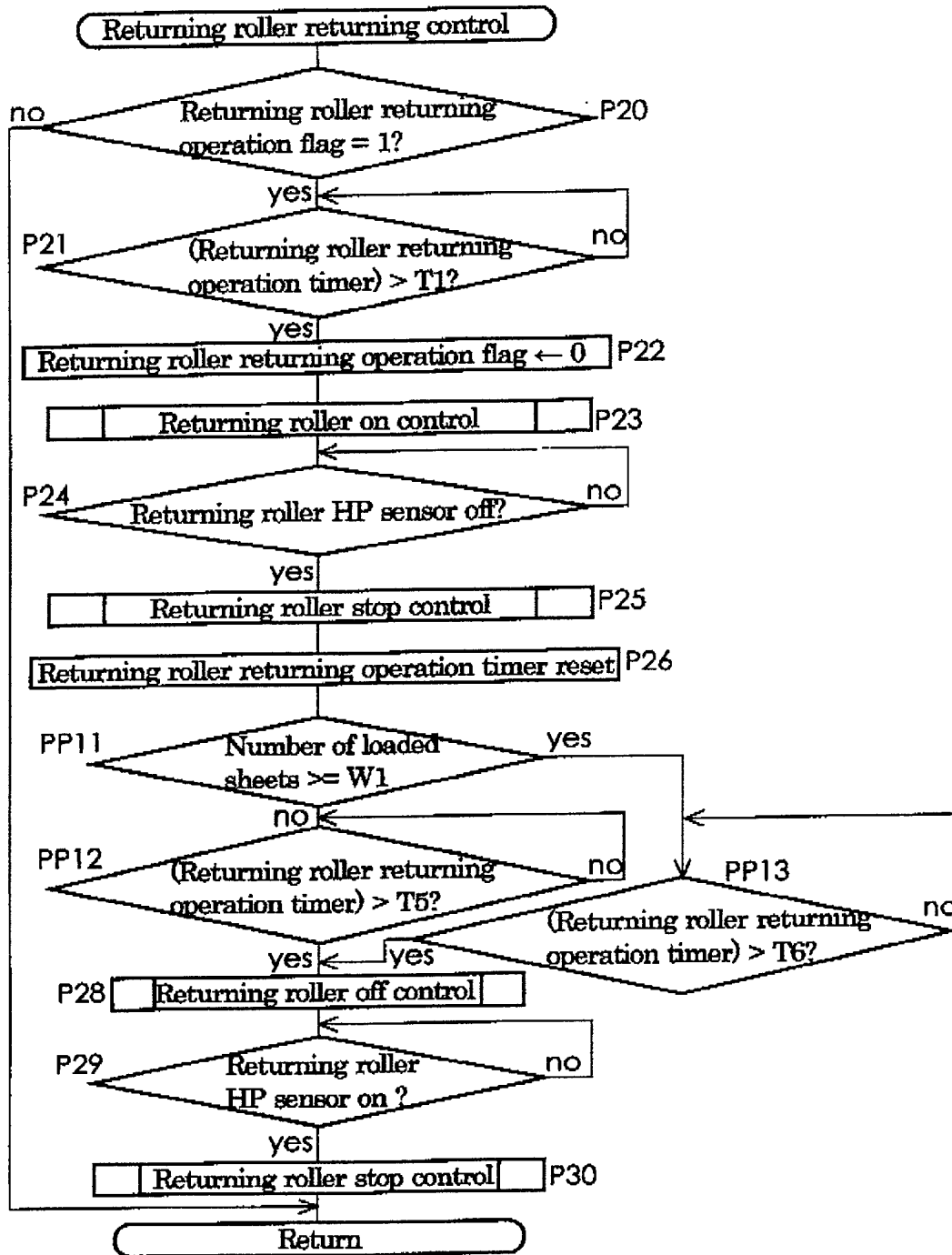
FIG. 41

Fig. 42



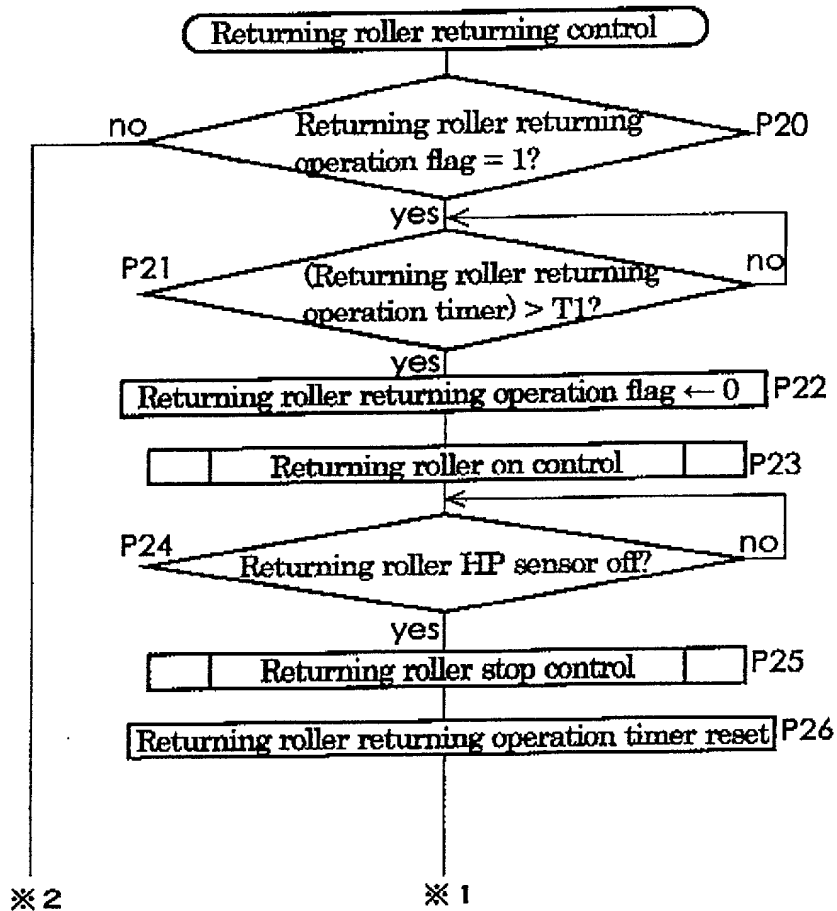
DOCKET "40E26560"

Fig. 43



FOOTNOTES 40E/6660

Fig. 44



DOCKET "40E26660"

Fig. 45

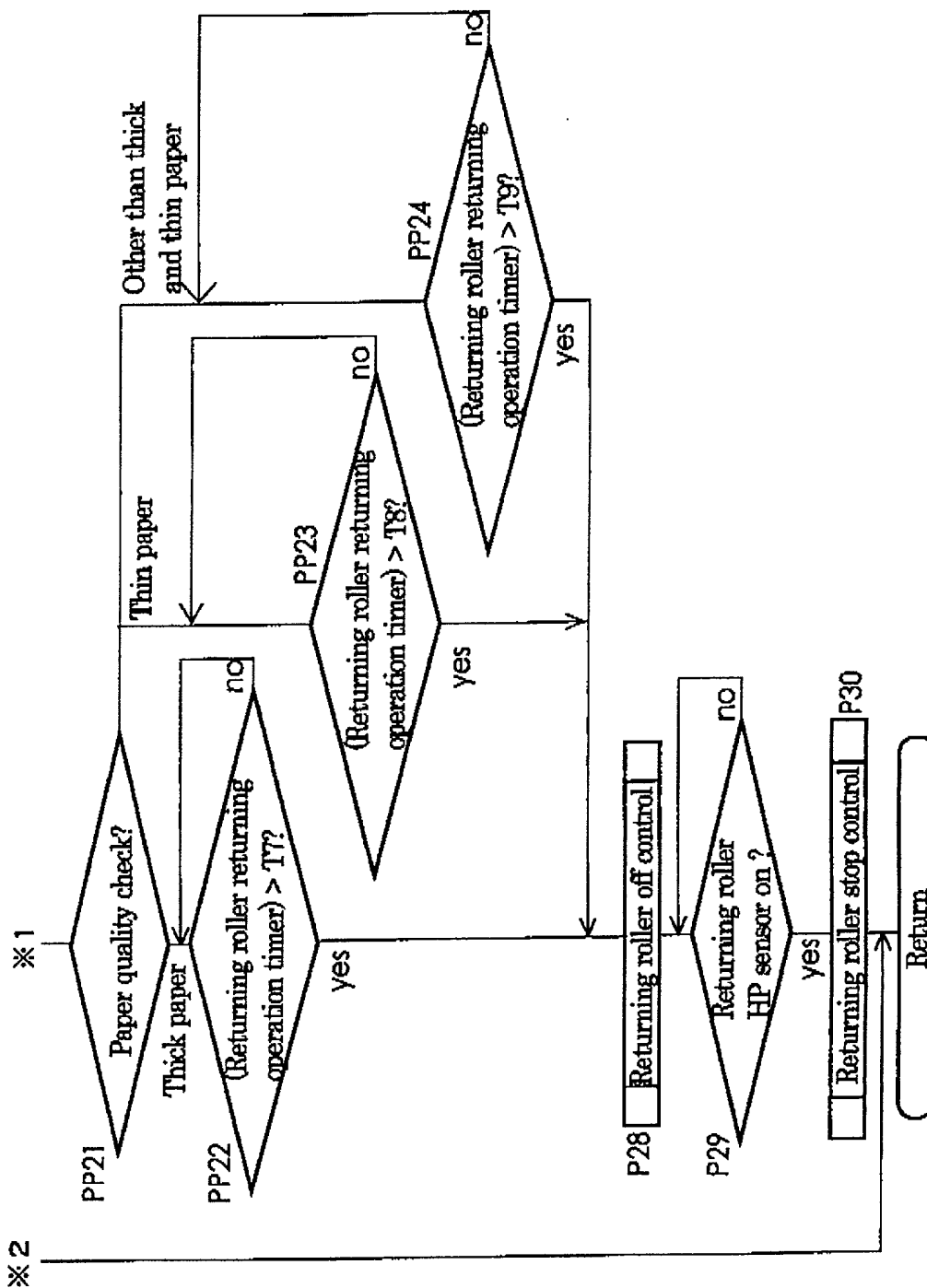
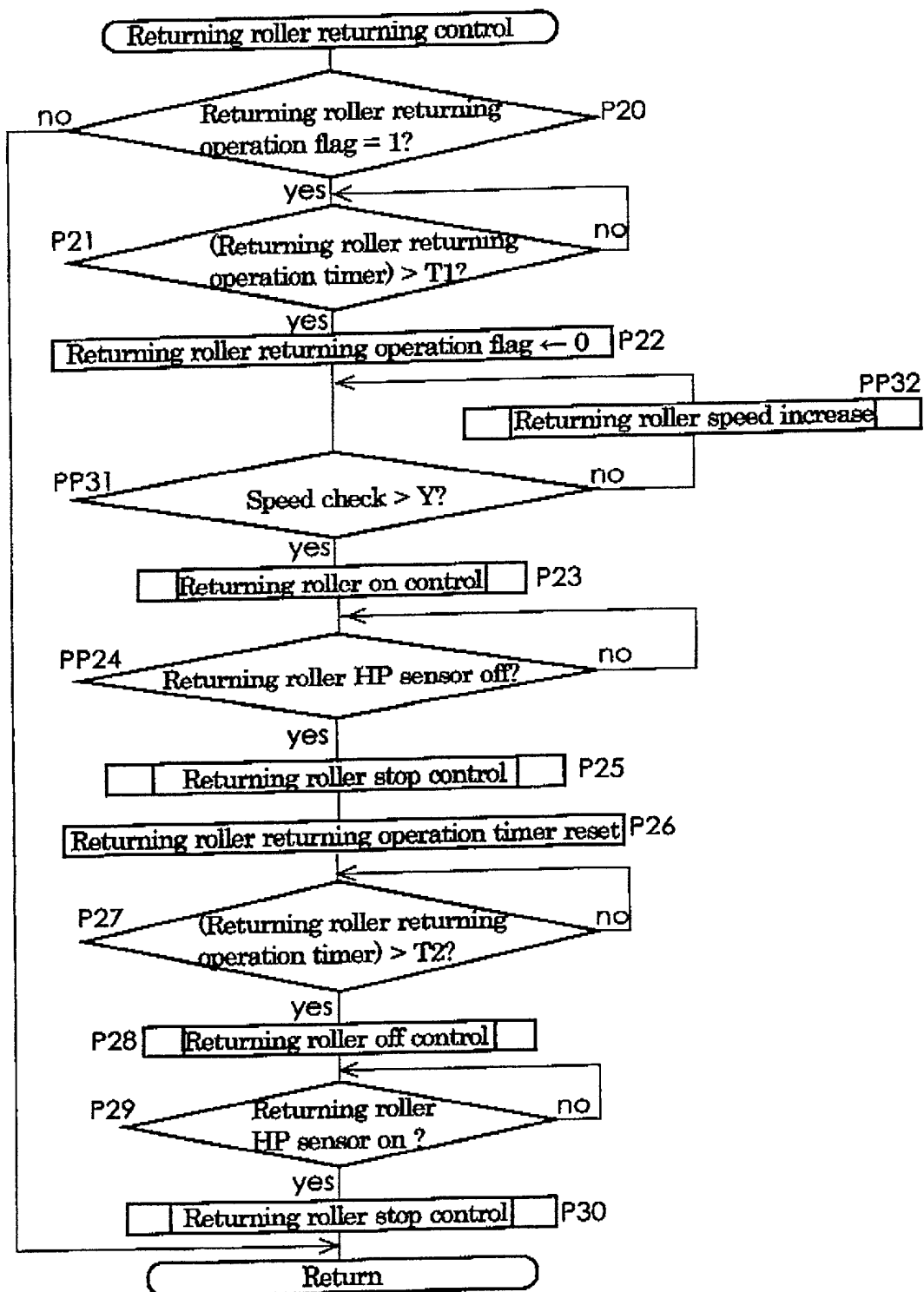
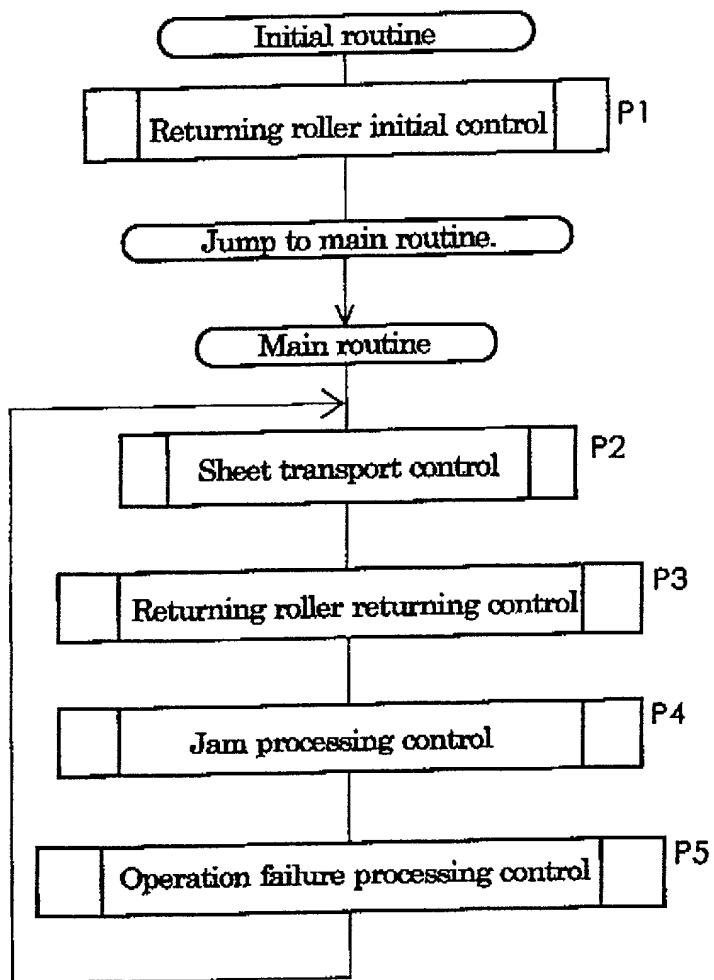


Fig. 46



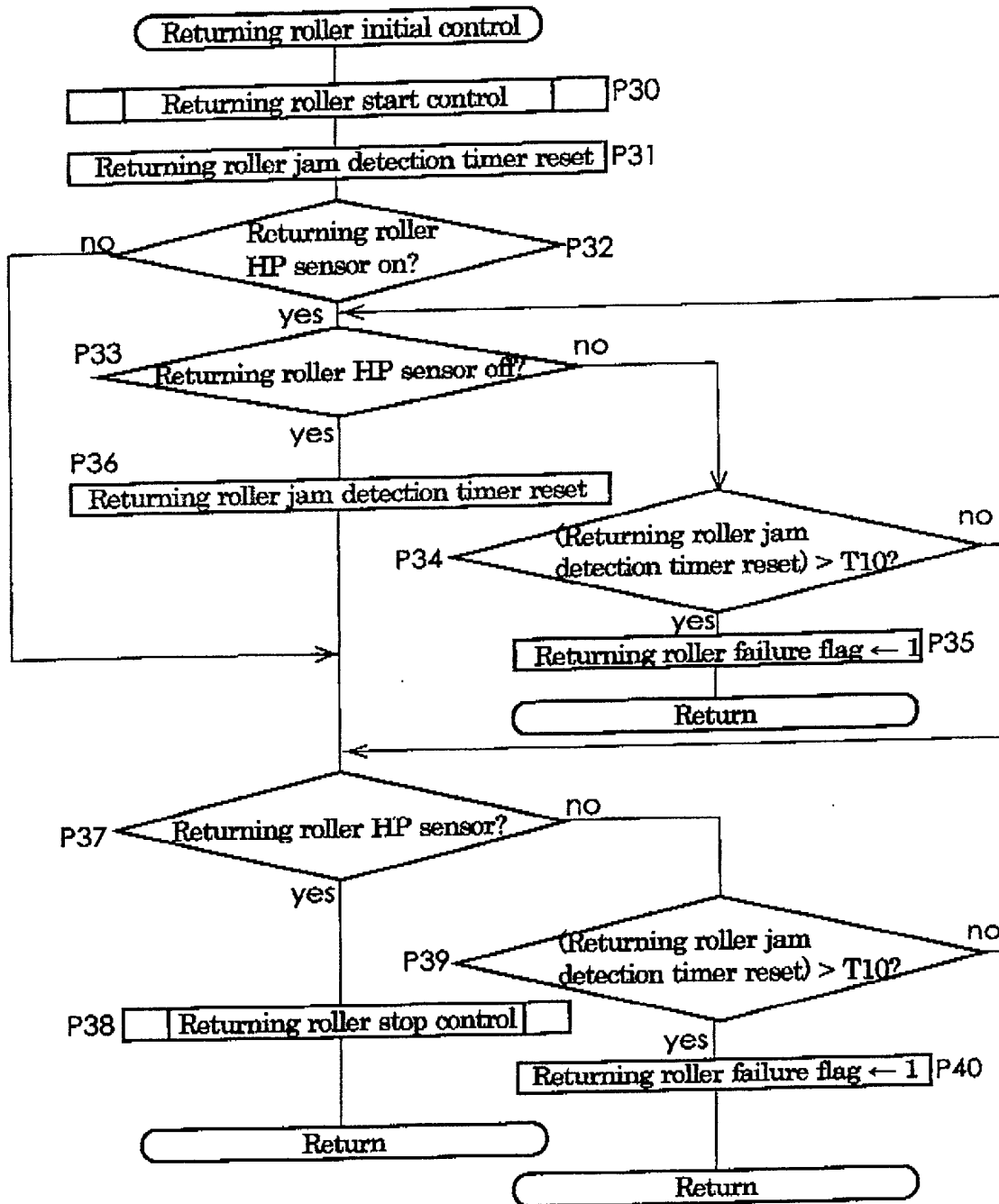
FOOTNOTES FOR FIG. 46

F i g . 4 7



DOCKET: 216630US2

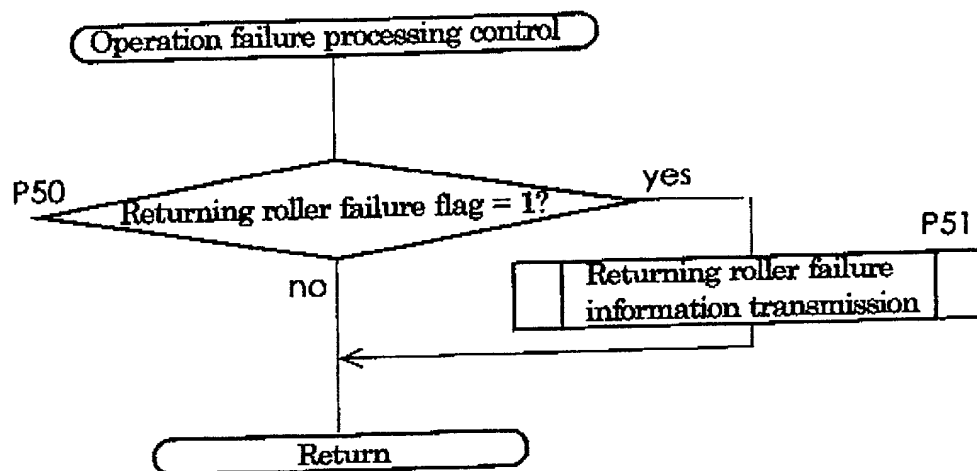
Fig. 48



00997304.13001



F i g . 4 9



DOCKET # 216630US2

Fig. 50

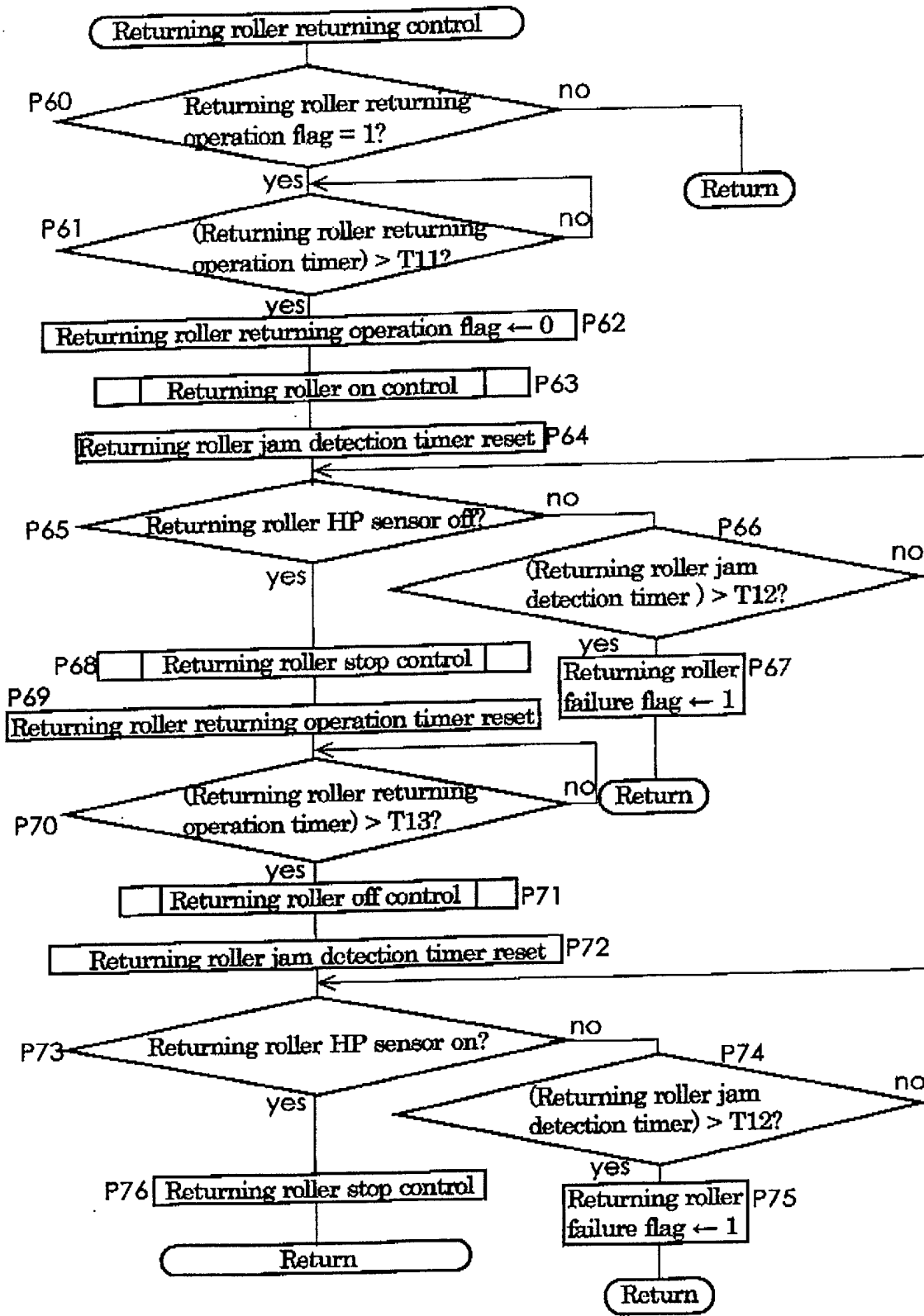


FIG. 50

15. F i s .

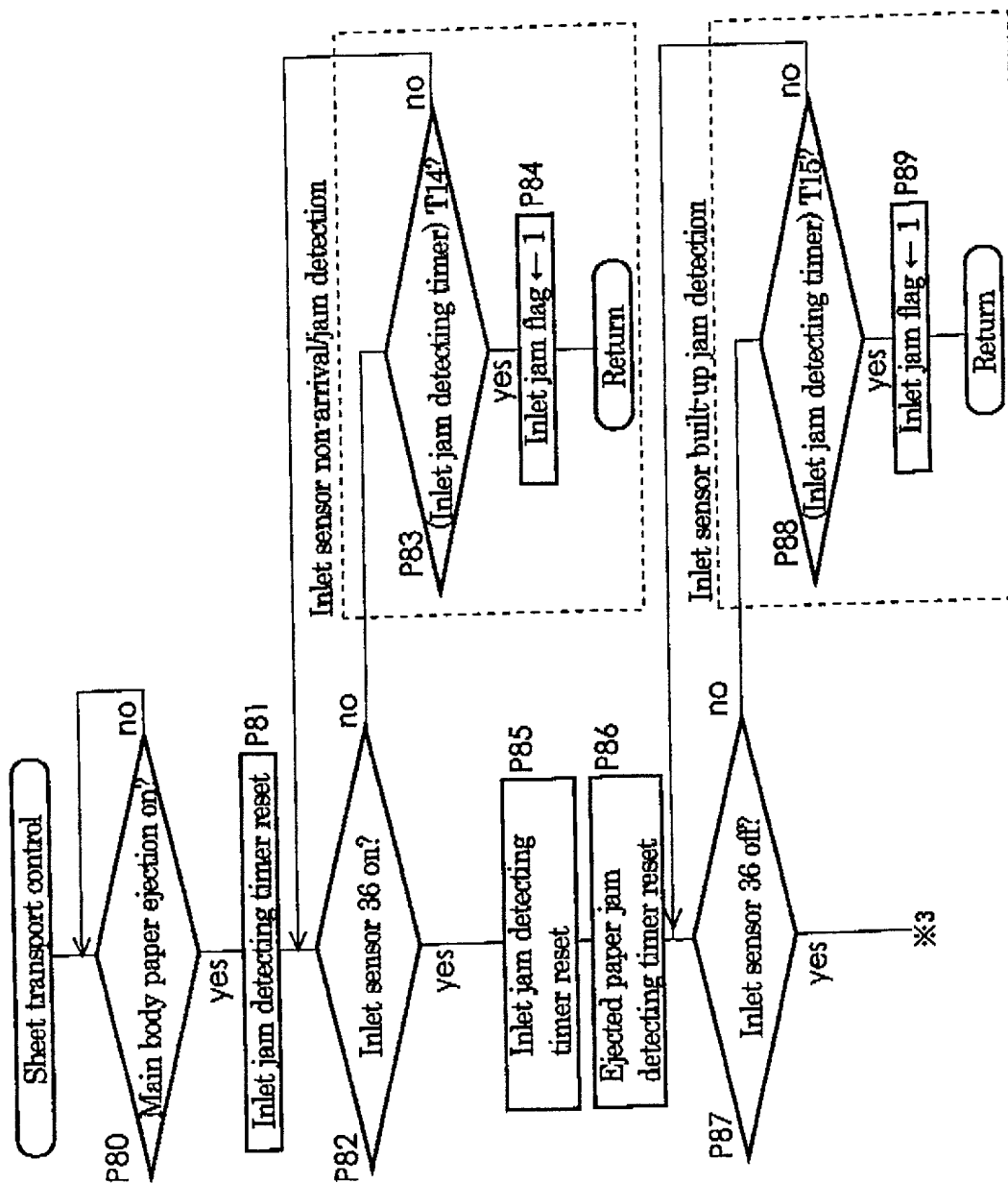


Fig. 52

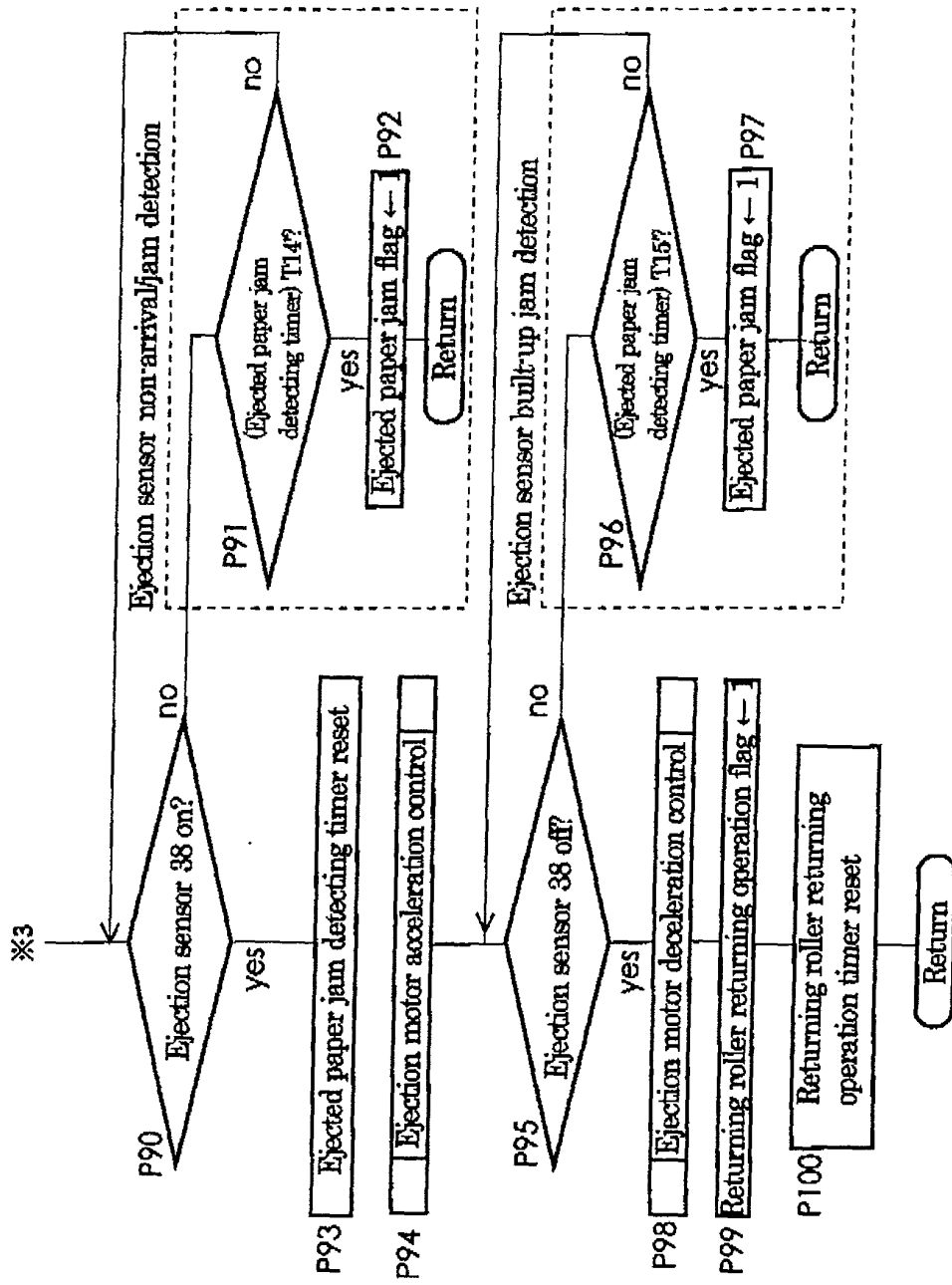


Fig. 53

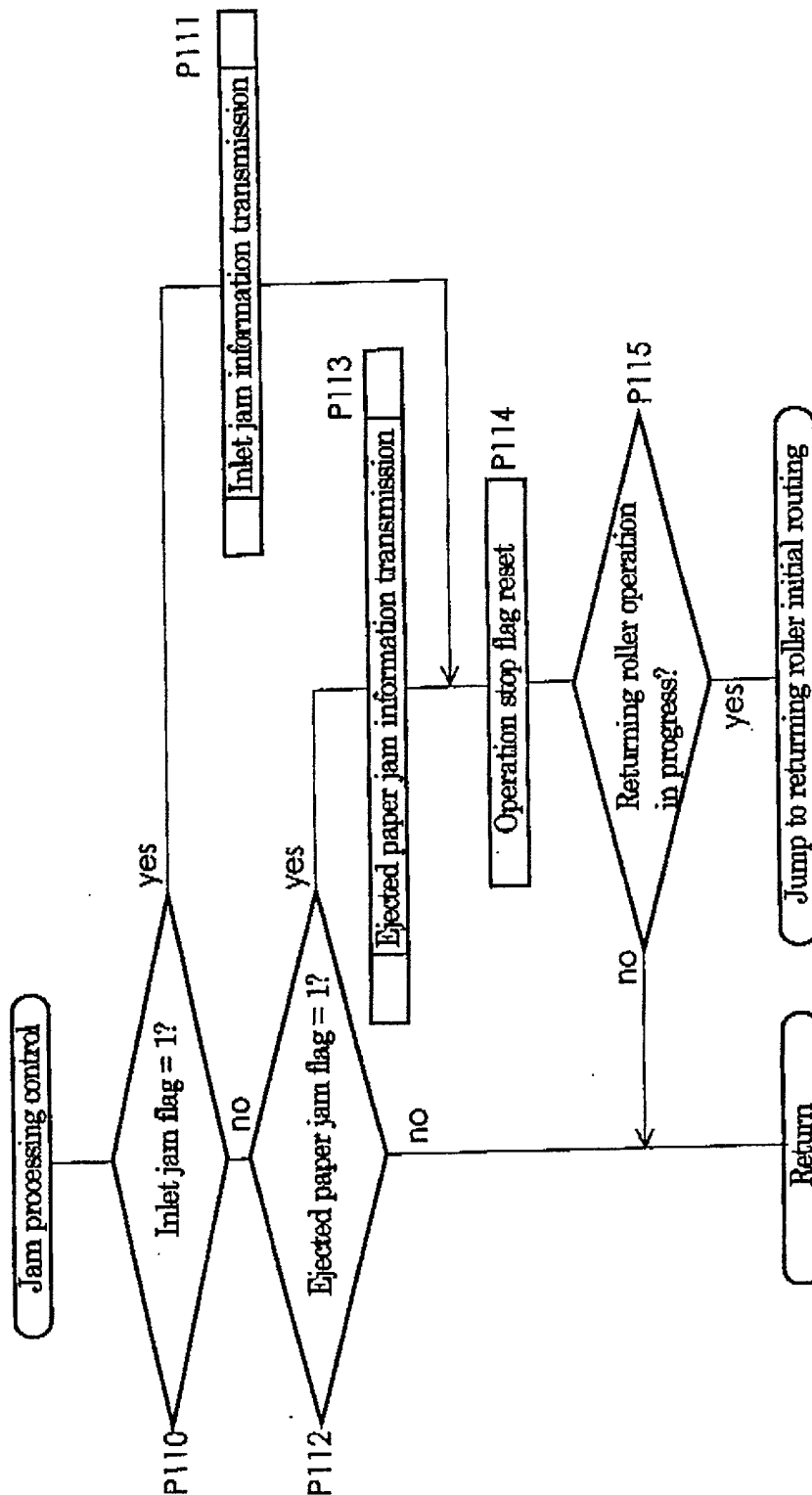


Fig. 54

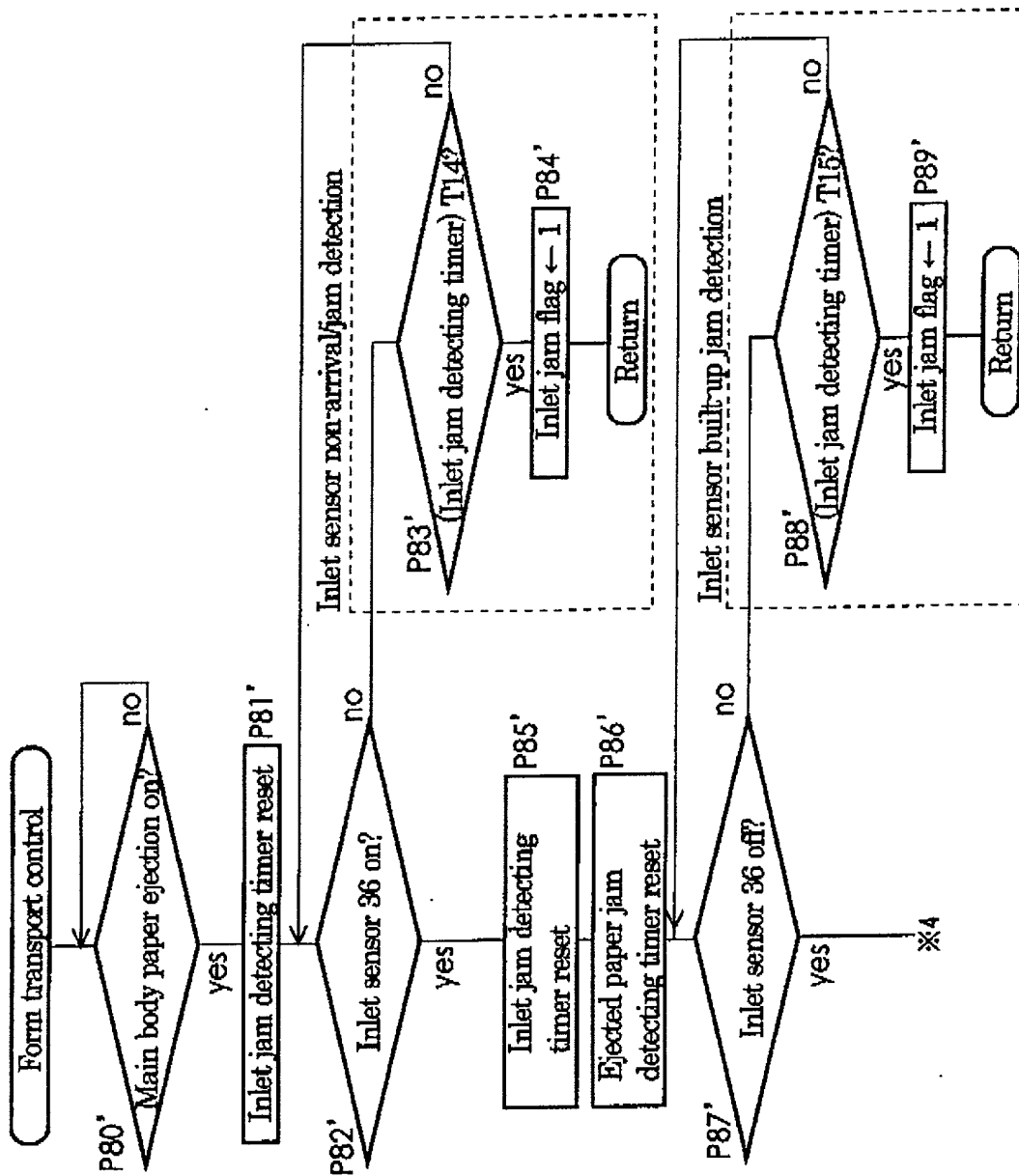


Fig. 55

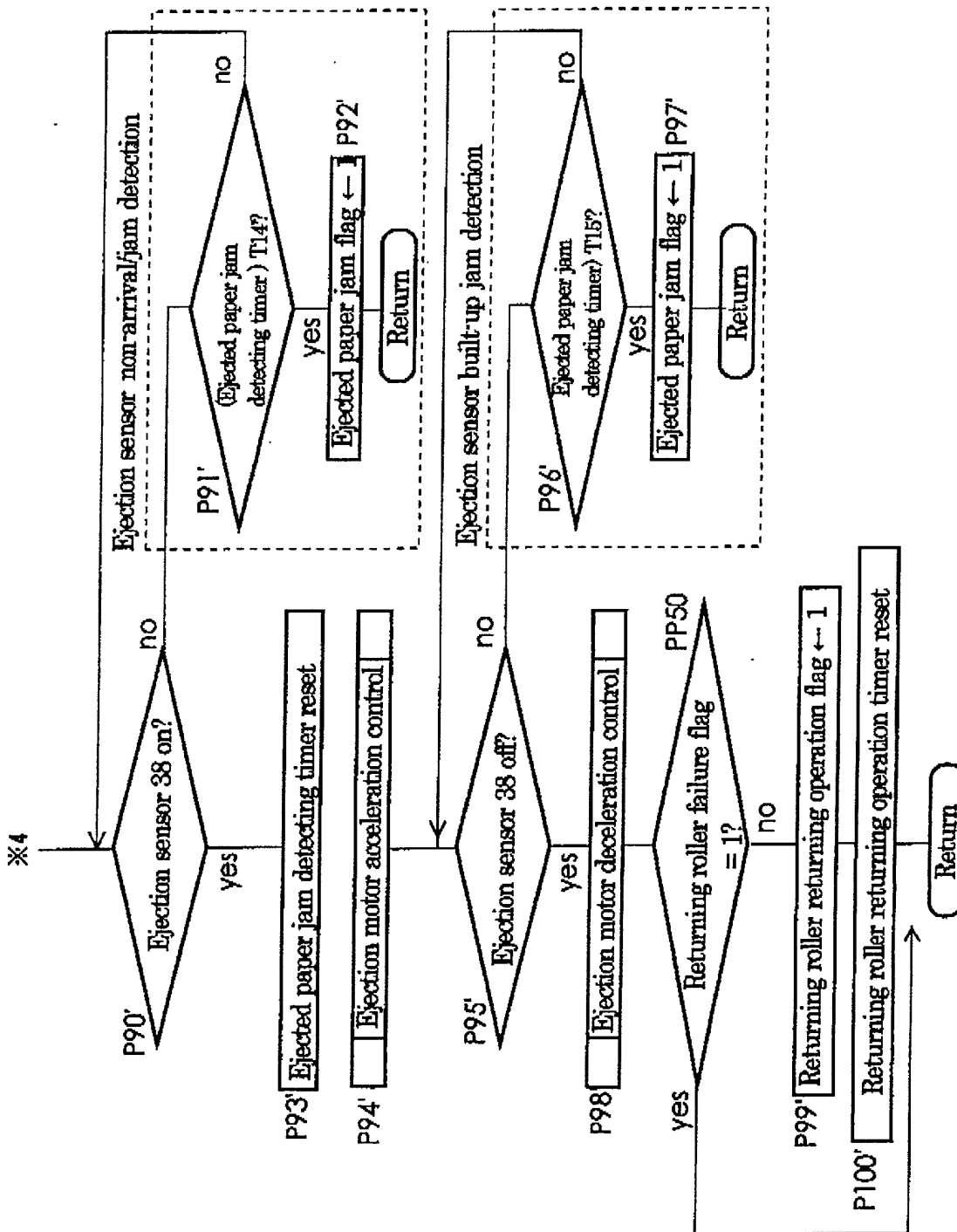
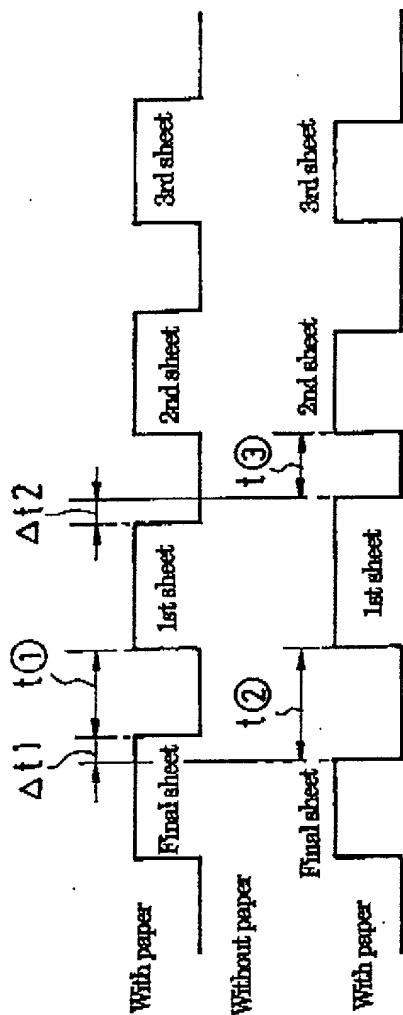


Fig. 56

(1) Output of ejection sensor 38

(Without acceleration/deceleration)



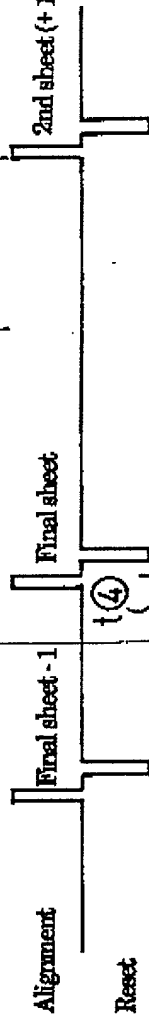
(2) Output of ejection sensor 38

(With acceleration/deceleration)

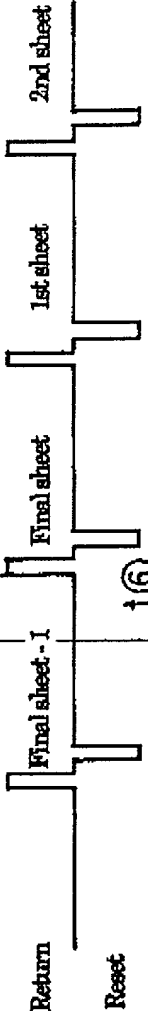


(3) Alignment operation

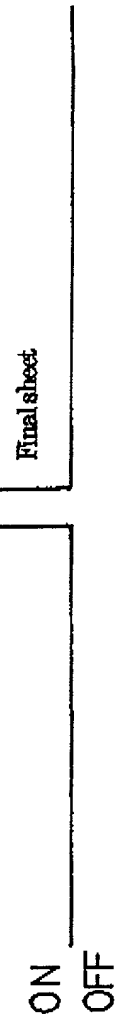
(jogger operation)



(4) Return Reset



(5) Sorting



t(1): Sheet interval (time) at receiving linear speed  
t(2): Sheet interval (time) in acceleration  
t(3): Sheet interval (time) in deceleration

t(4): Timer value P in Fig. 37  
t(5): Timer value Q in Fig. 38  
t(6): Timer value R in Fig. 39



(Front)

(Rear)

(Home position)

**Fig. 59**

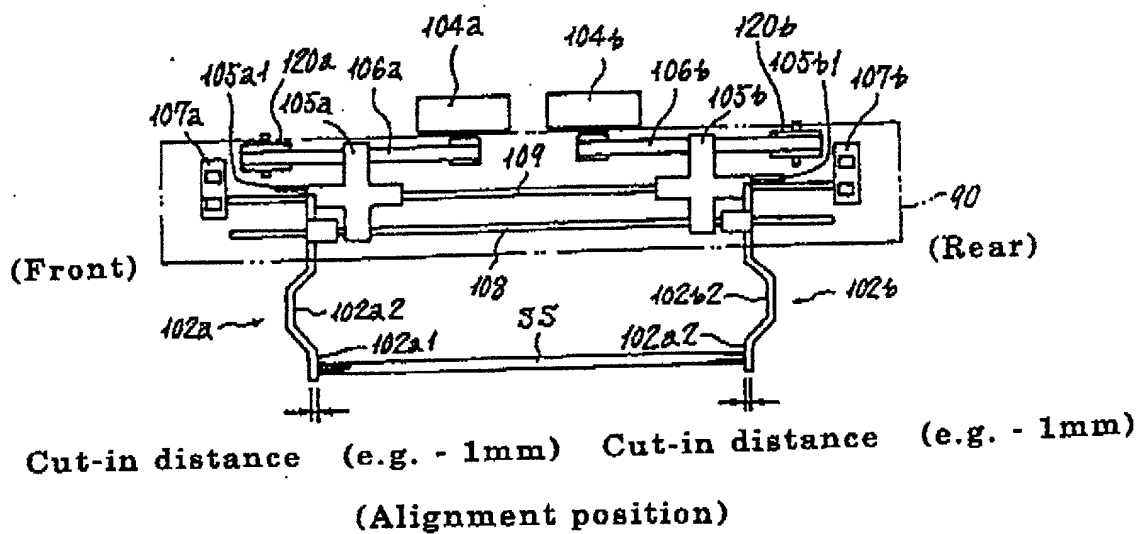
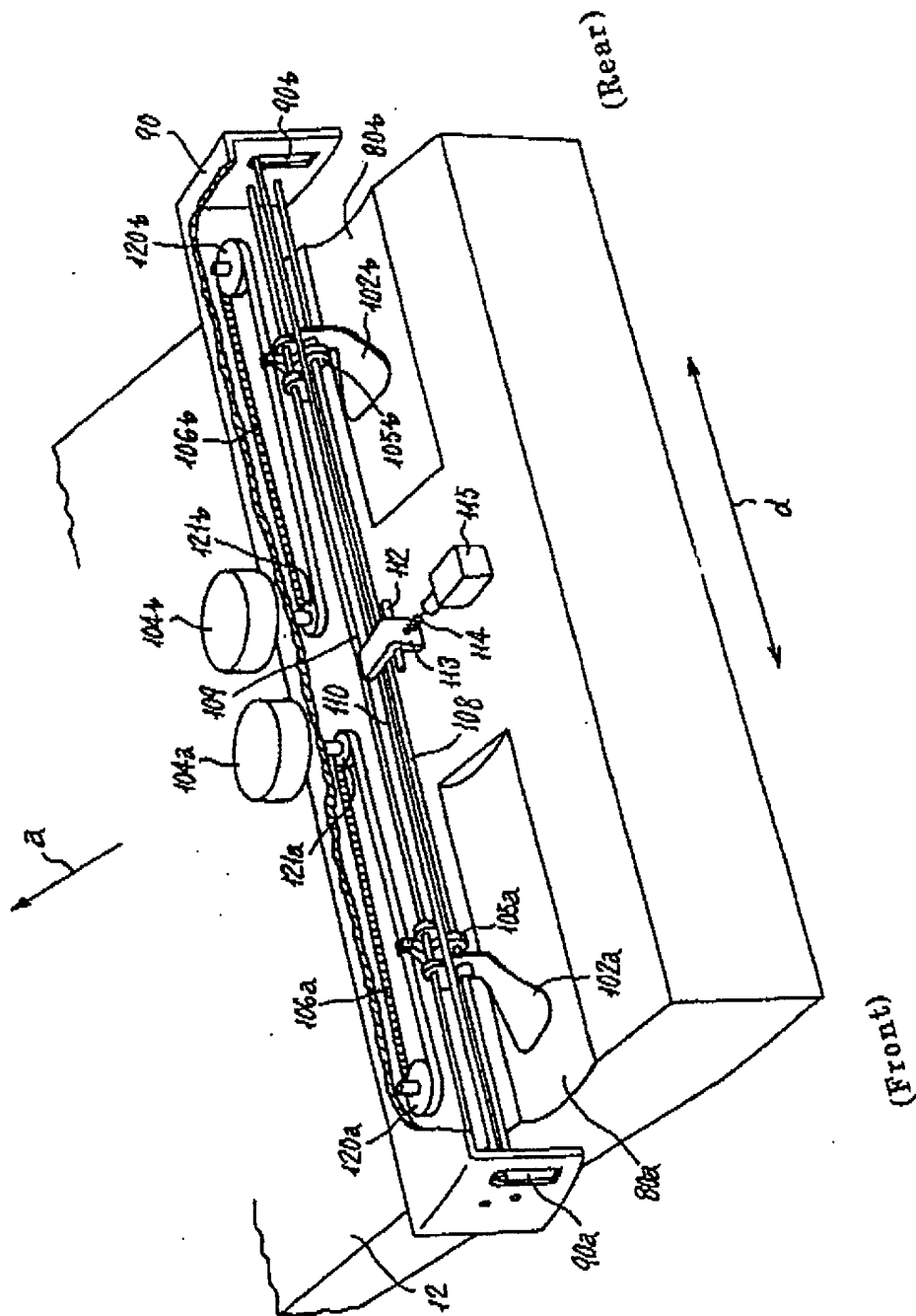
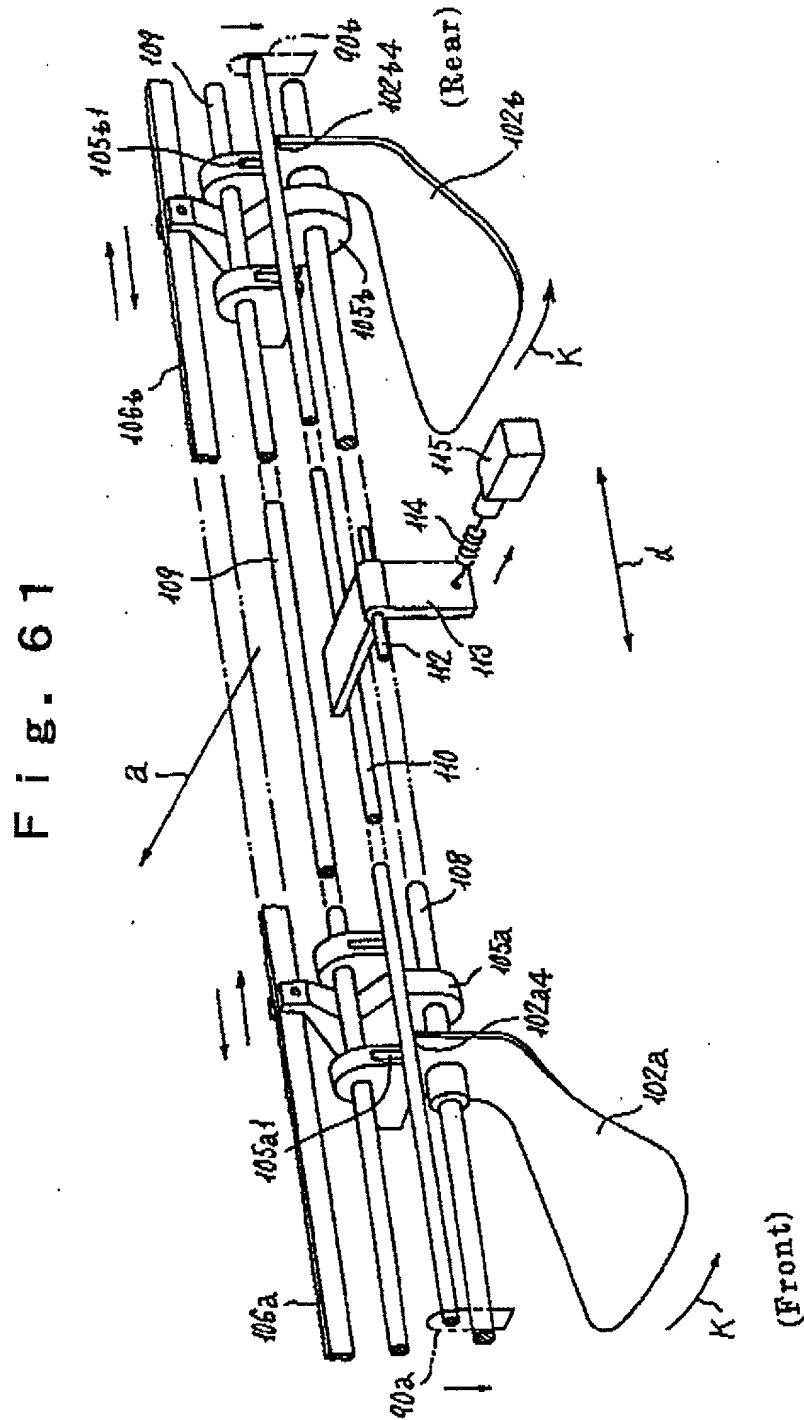


Fig. 60





File 62

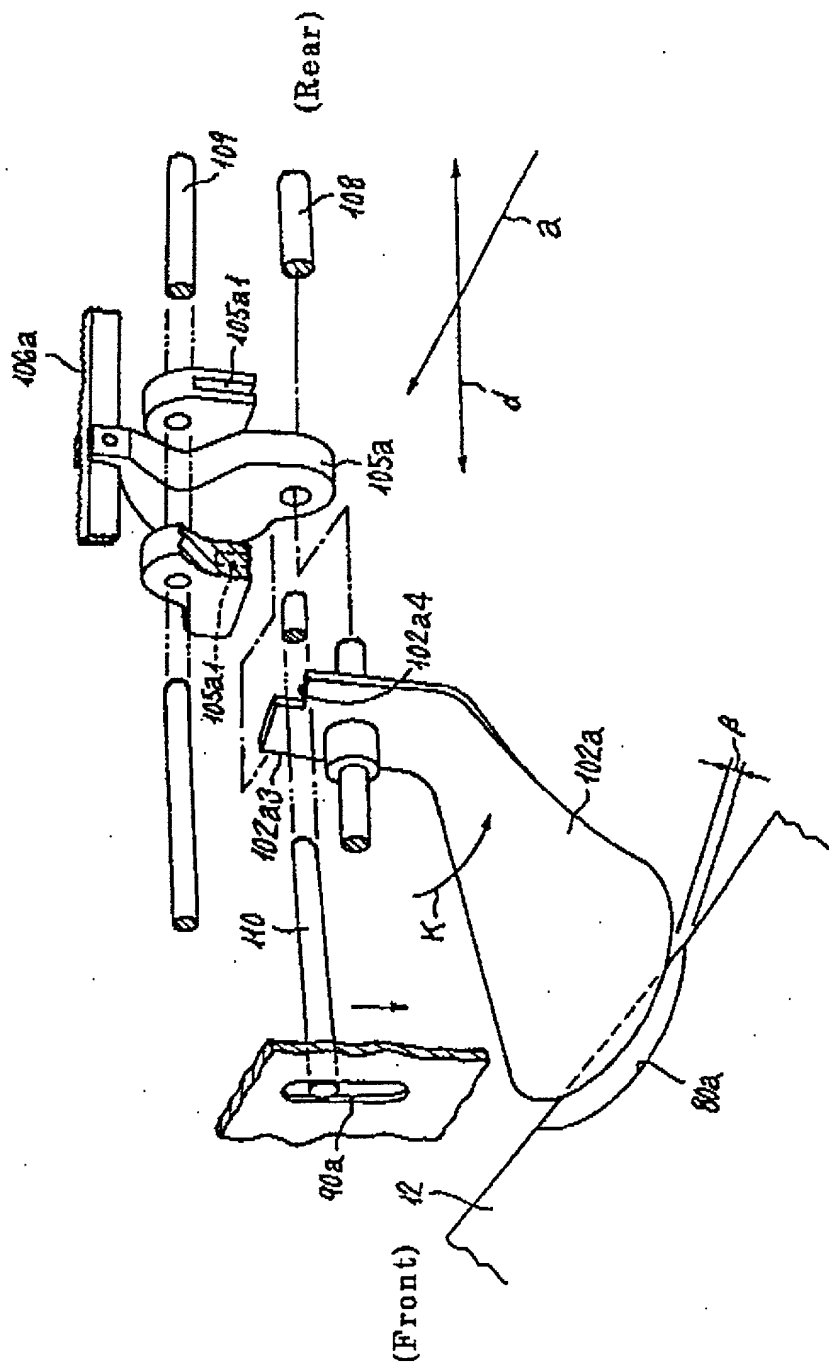


Fig. 63

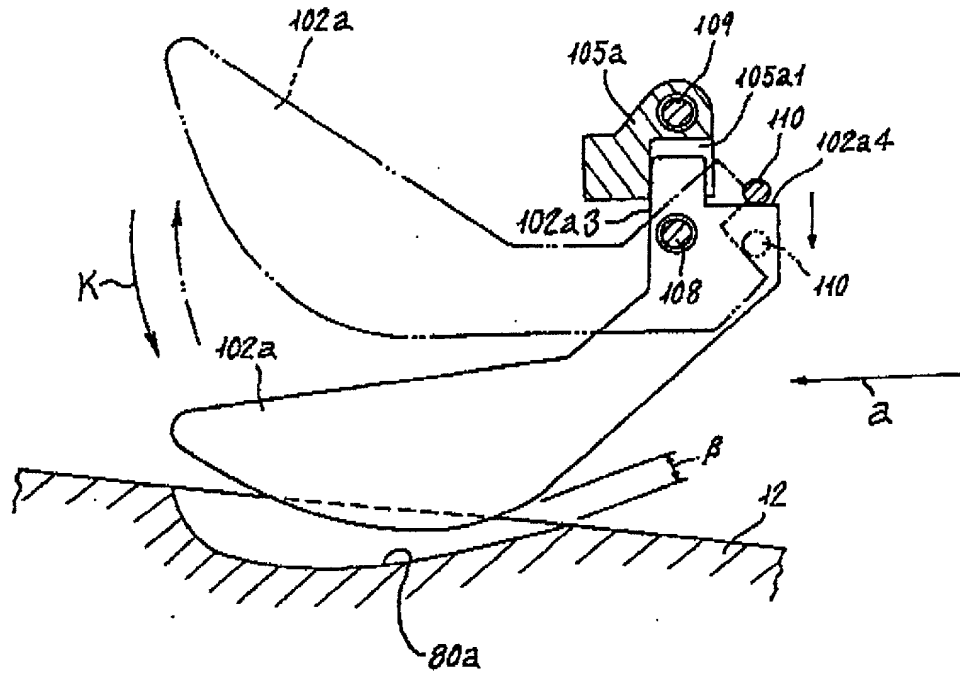
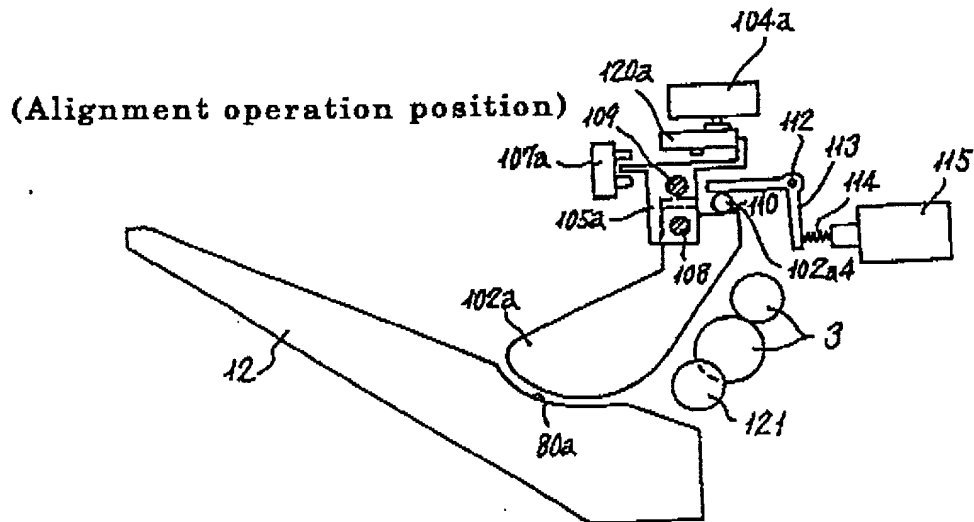
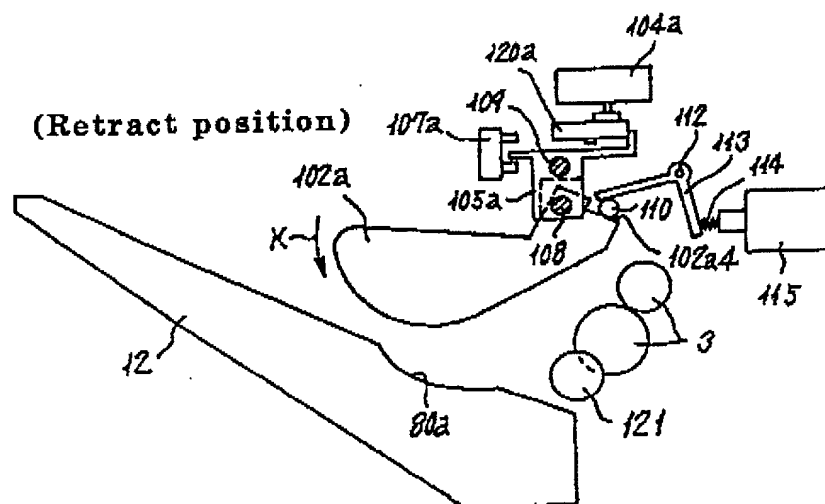


Fig. 64



F i g . 6 5



FOOTPRINT 40E26660

Fig. 66 (a)

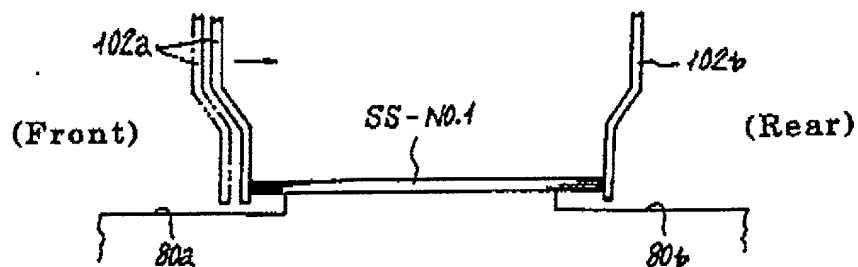


Fig. 66 (b)

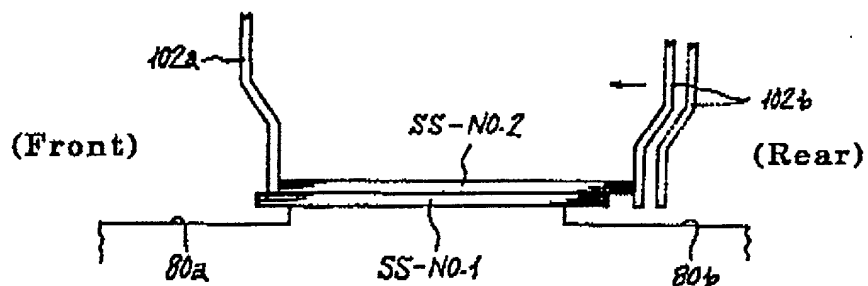


Fig. 66 (c)

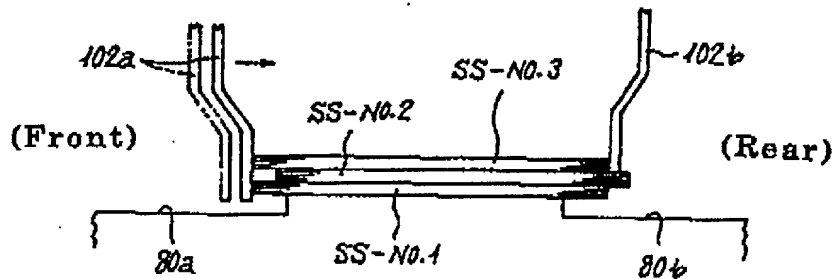
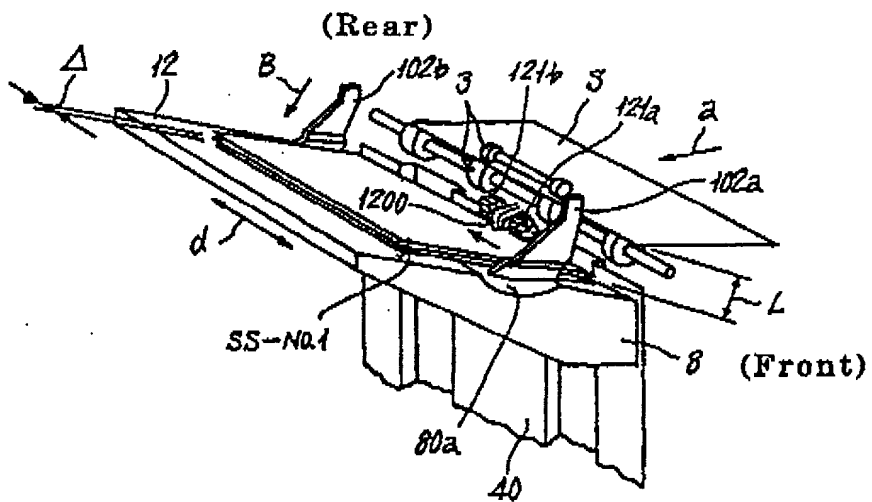


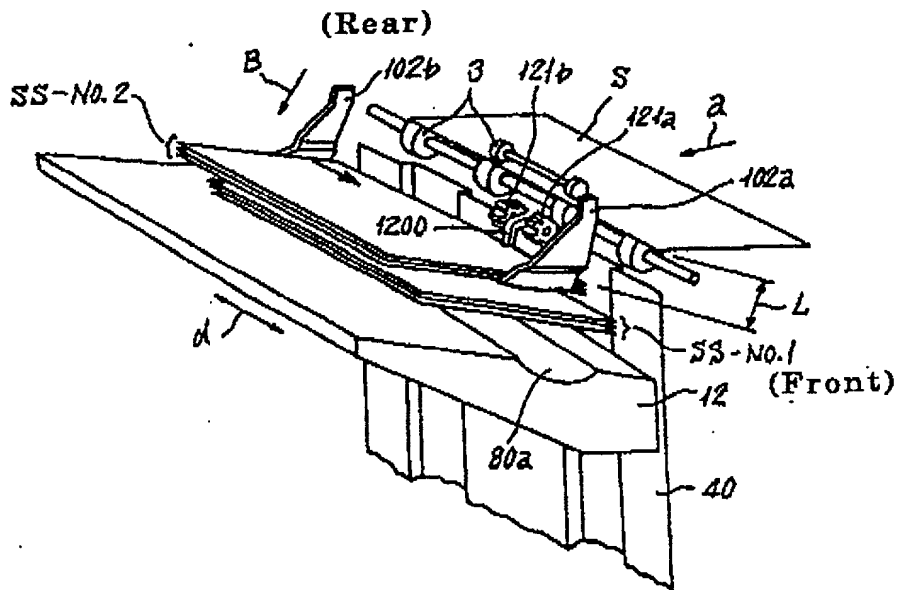
FIG. 66 (a) (b) (c)



**F i g . 6 7**



**F i g . 6 8**



(Rear)

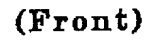


Fig. 70 (a)

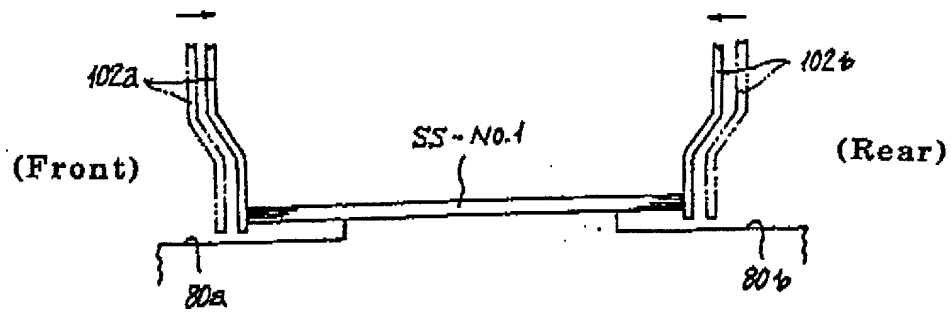


Fig. 70 (b)

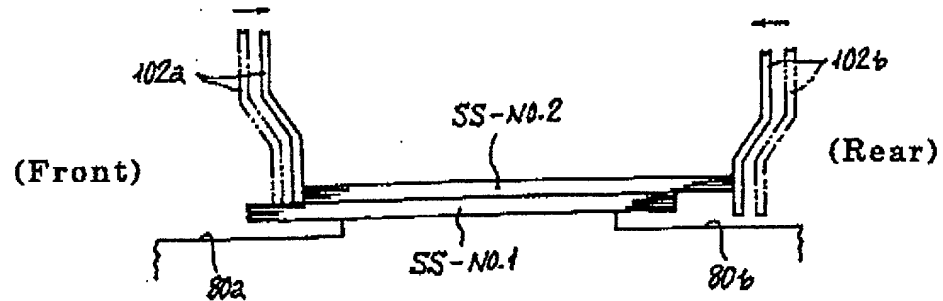


Fig. 70 (c)

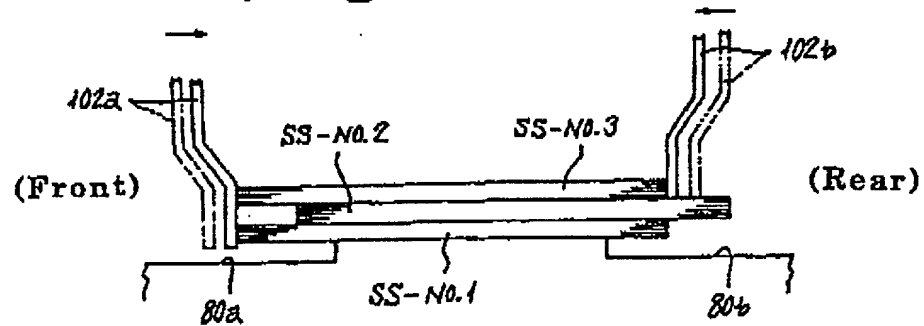
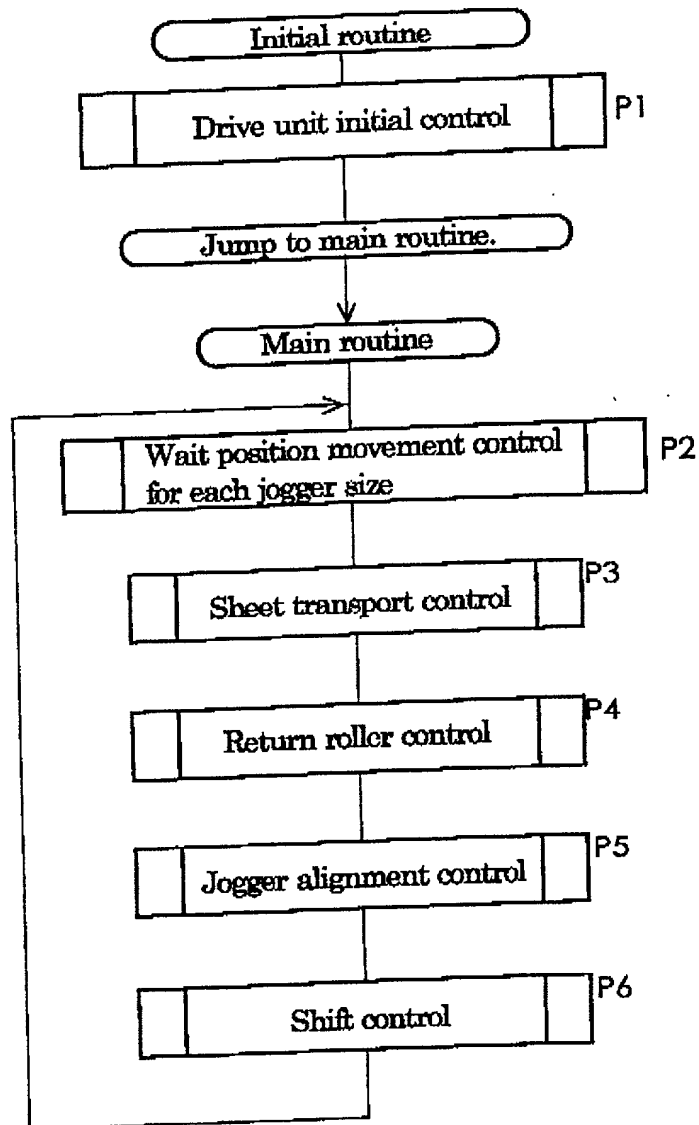
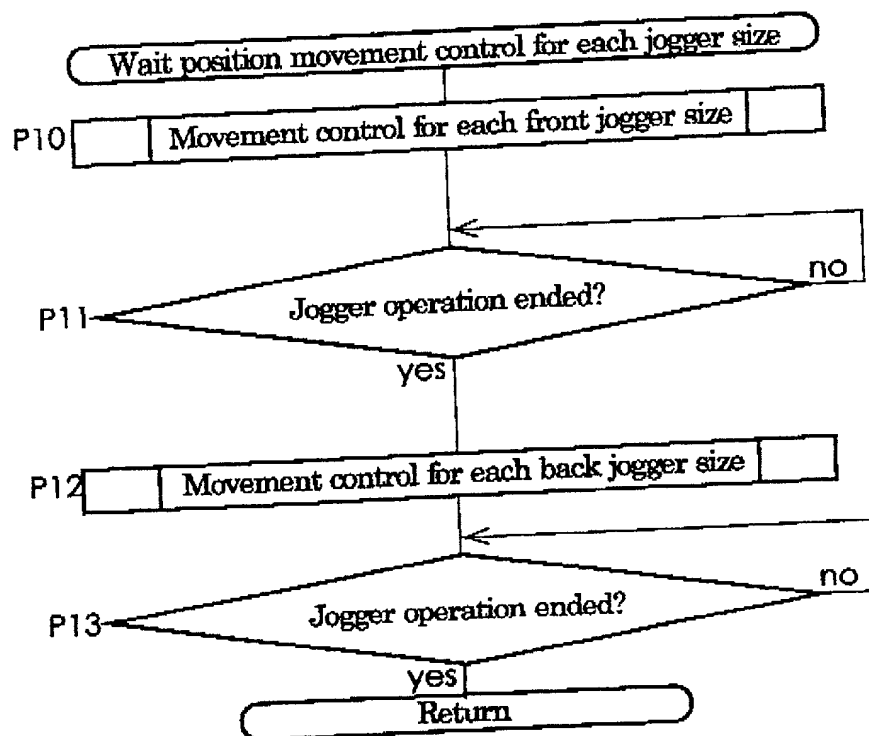


Fig. 71



DOCKET # 216630US2

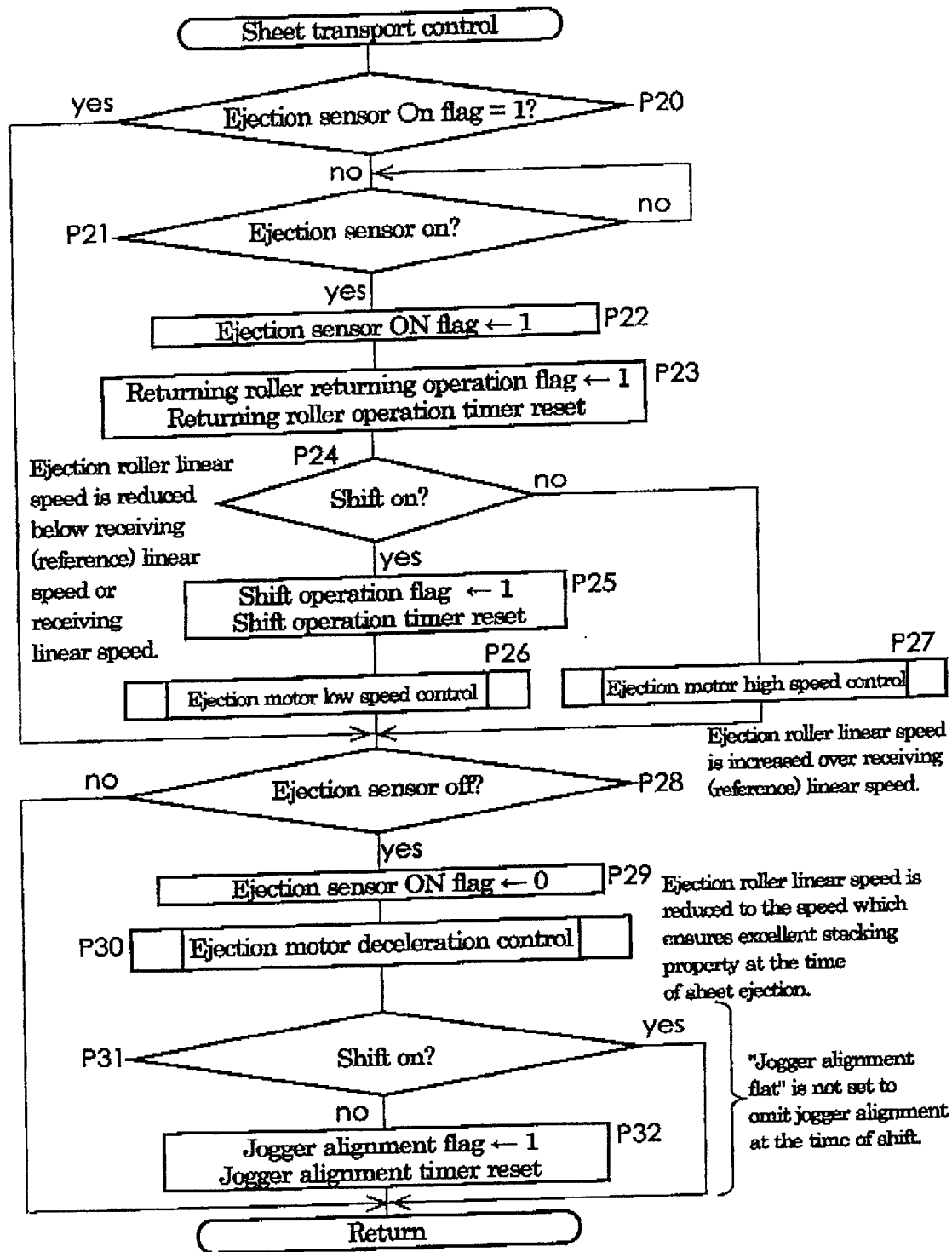
Fig. 72



Front jogger: alignment 102a  
Back jogger: alignment 102b

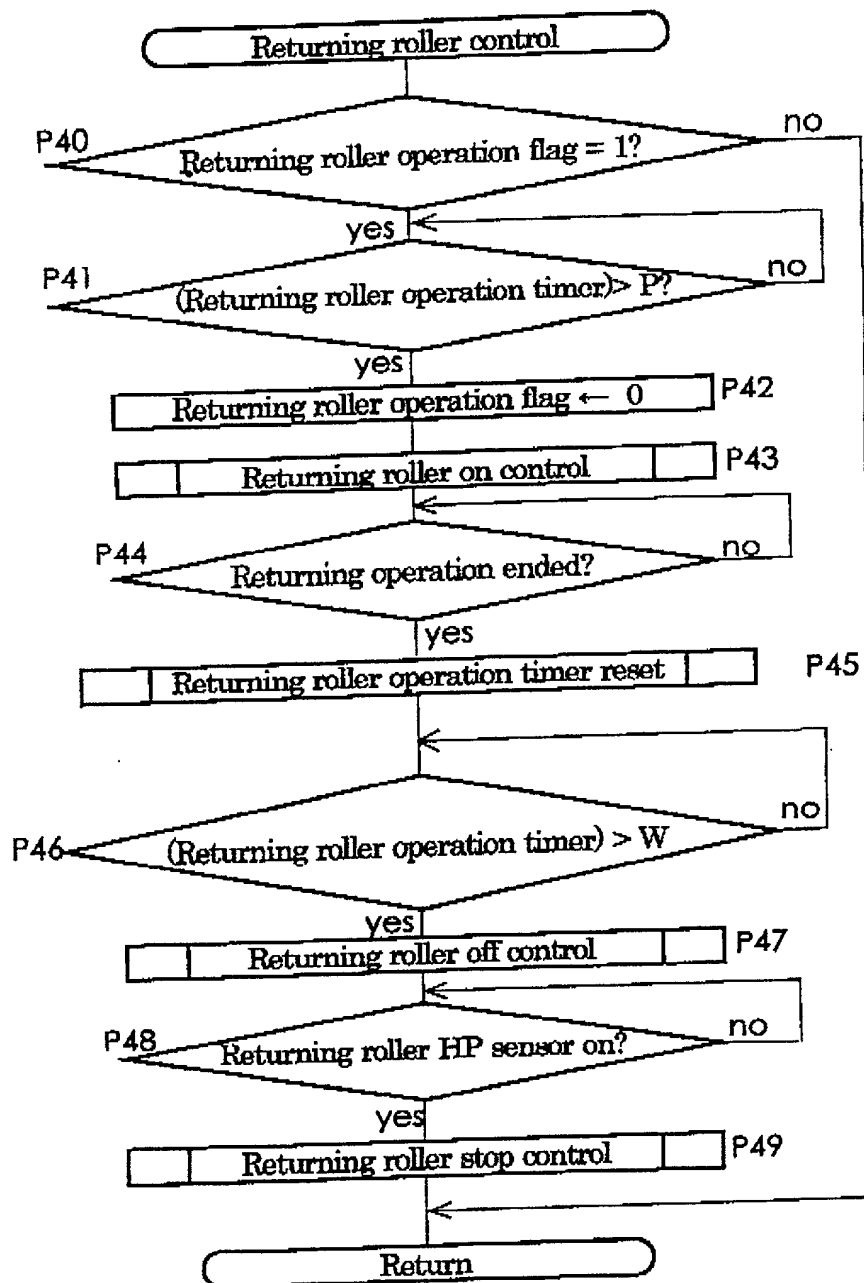
DOCKET "406/6660"

Fig. 73



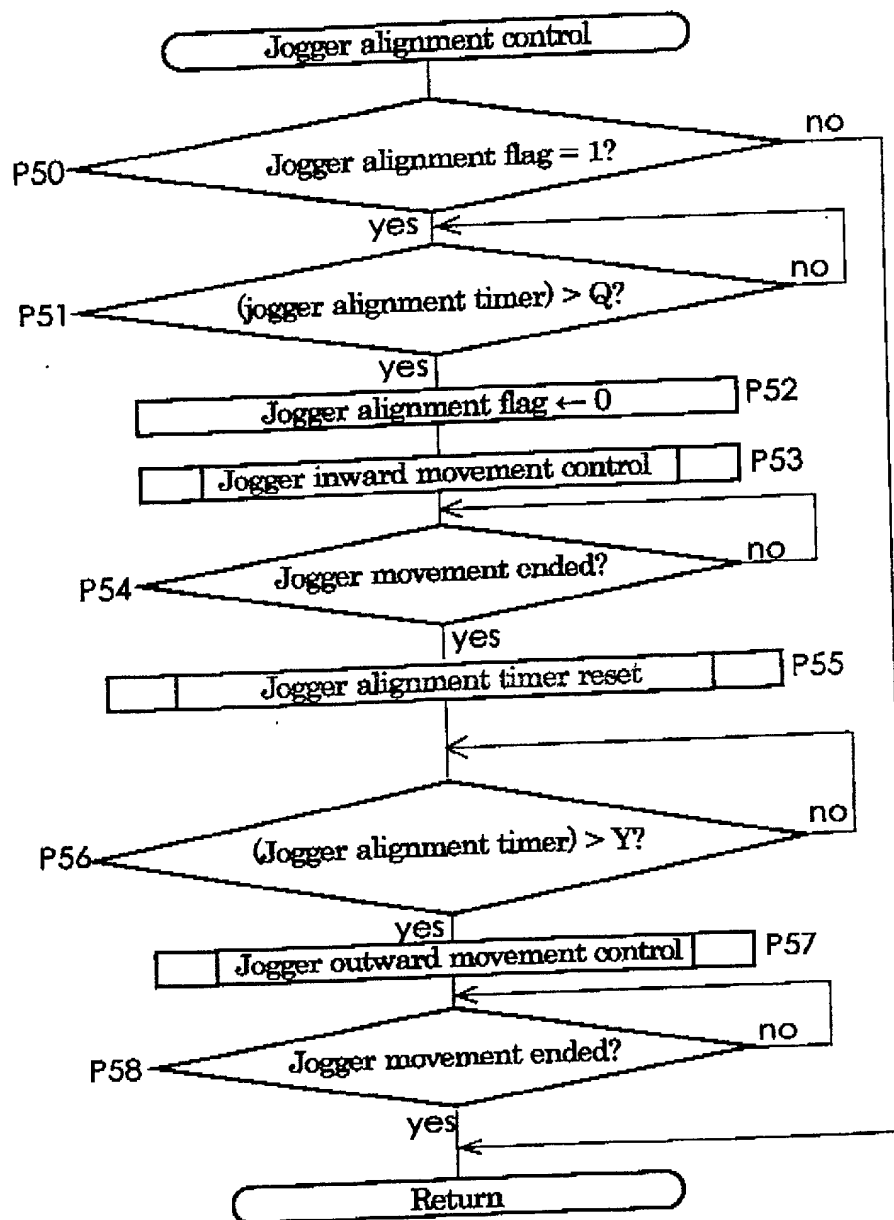
DOCKET # 216630US2

Fig. 74



DOCKET # 216630US2

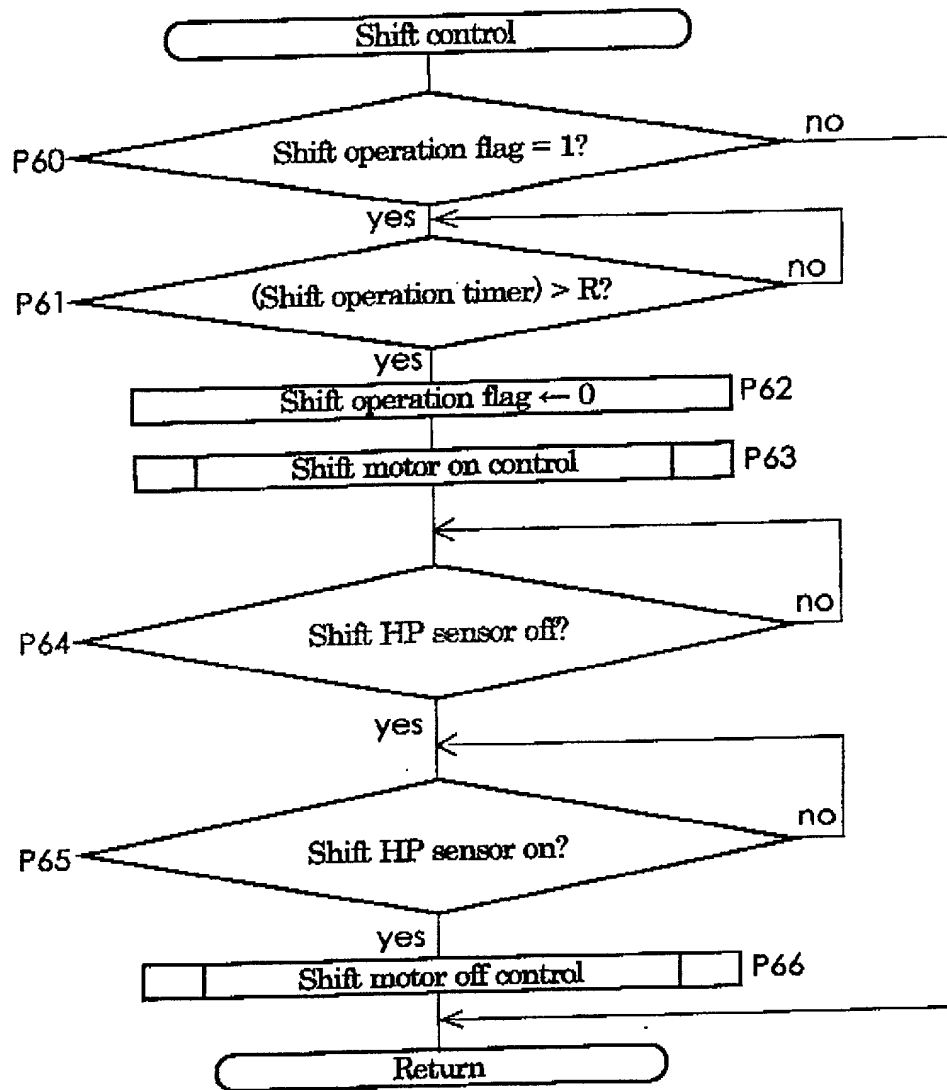
Fig. 75



FOOT "40E/6660



Fig. 76



DOCKET # 216630US2

F i g . 77

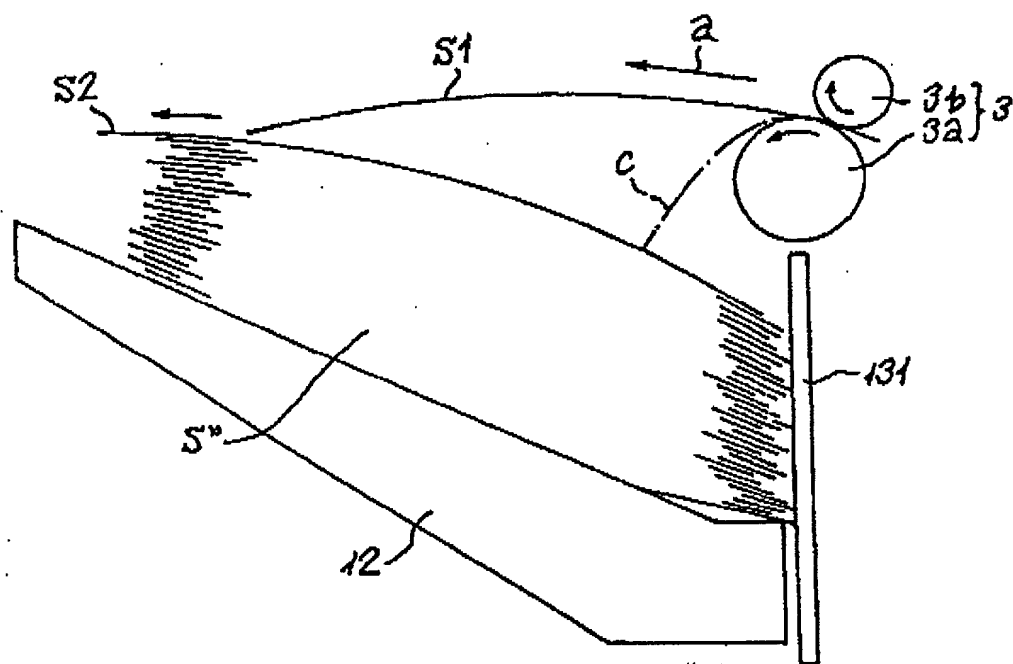




Fig. 79

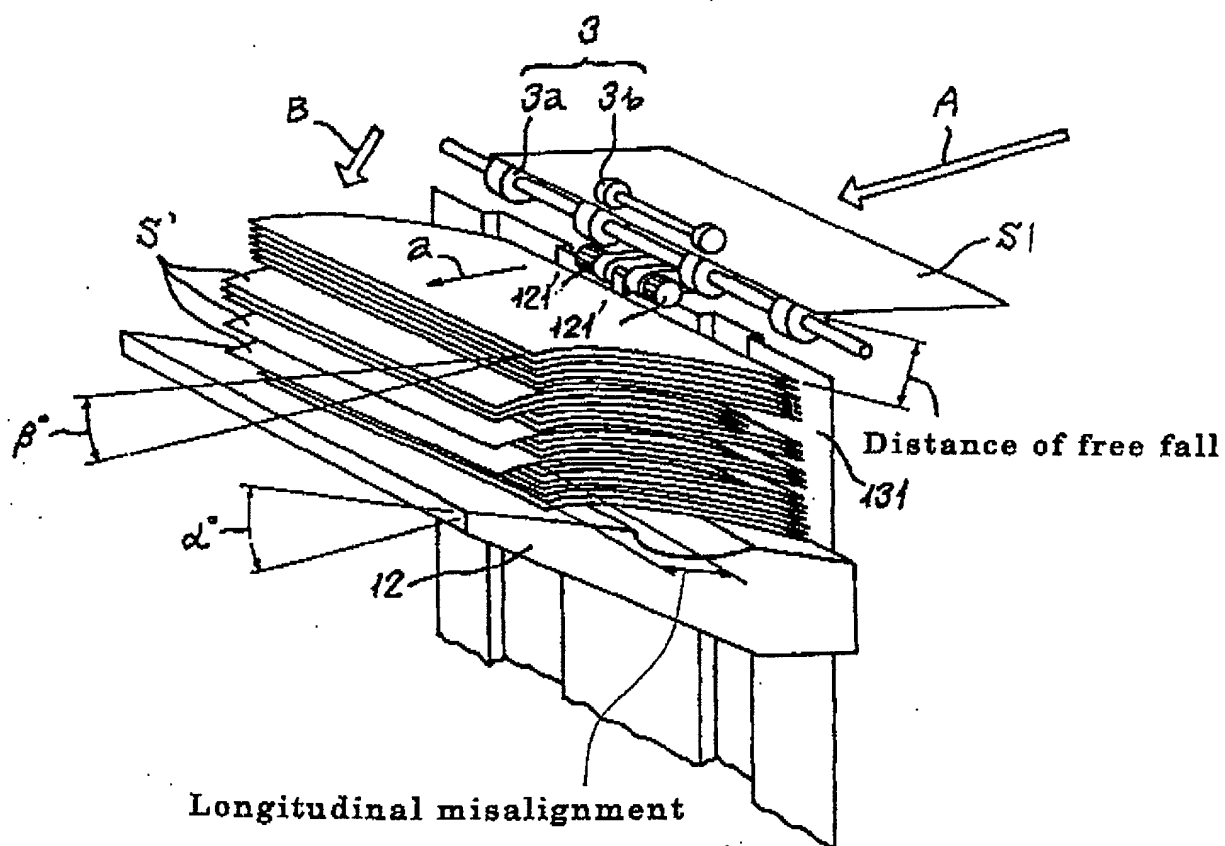
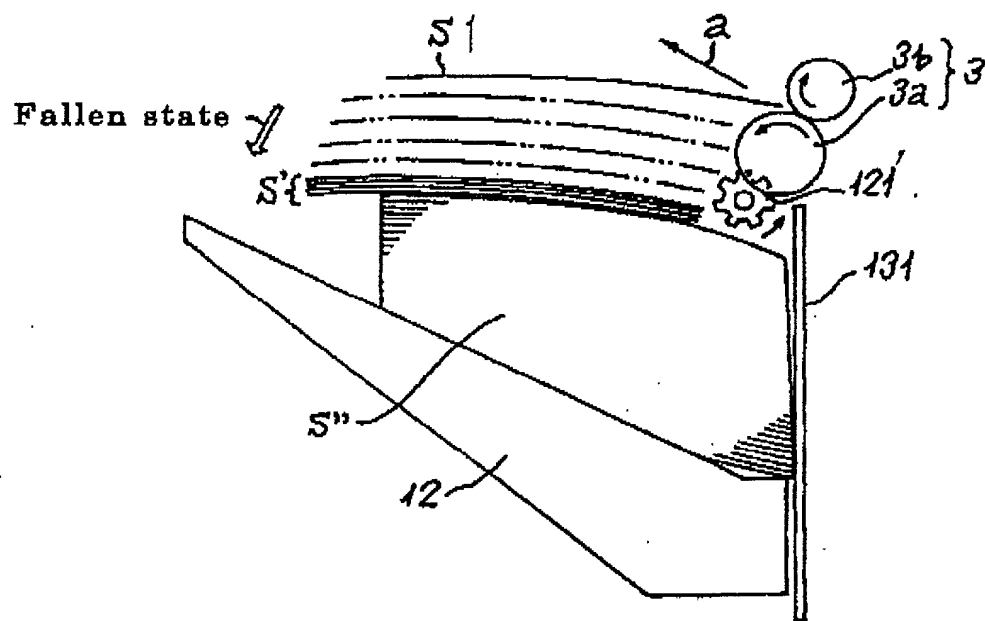


Fig. 80



DOCKET# 216630US2